

Rotary Clamp CylinderSeries MK(Standard type)<br/>ø12, ø16, ø20, ø25, ø32, ø40, ø50, ø63Series MK2(Heavy duty type)<br/>ø20, ø25, ø32, ø40, ø50, ø63



## Series MK/MK2

## A Precautions 1

Be sure to read before handling. For Safety Instructions and Actuator Precautions, refer to pages 10-24-3 to 10-24-6.

#### **Operating Environment**

## \land Warning

Do not use the cylinder under following environments:

- **1.** An area in which fluids such as cutting oil splash on the piston rod.
- **2.** An area in which foreign matter such as particles, cutting chips, dust, or spatter is present.
- **3.** An area in which the ambient temperature exceeds the operating range.
- 4. An area exposed to direct sunlight.
- 5. An environment that poses the risk of corrosion.

#### **Removing and Reinstalling the Clamp Arm**

## \land Warning

To remove and reinstall the arm on the piston rod, instead of securing the cylinder body, use a wrench to secure the arm to loosen or to tighten the bolt (Fig. (1)).

An excessive amount of rotational force will be applied to the piston rod if the bolt is tightened by securing the cylinder body, which could damage the internal parts.

To fabricate an arm, make sure to machine a detect portion that corresponds to the parallel section at the rod end.



Fig. (1)

#### **Speed Adjustment**

## **Warning**

Make sure to connect a speed controller to the cylinder and adjust it so that the cylinder speed will be within a range of 50 to 200 mm/s. If a clamp arm other than the available option is used, make sure to select an appropriate arm after calculating the inertial moment of the arm.

To operate a speed controller, make sure that the valve is fully closed, and gradually open the valve to adjust the speed.



## A Precautions 2

Be sure to read before handling. For Safety Instructions and Actuator Precautions, refer to pages 10-24-3 to 10-24-6.

#### How to Operate

## \land Warning

The MK cylinder could malfunction or the non-rotating accuracy could be affected if a rotational force is applied to the piston rod. Therefore, observe the particulars given below before operating the cylinder.

1. Make sure to mount the cylinder vertically (Fig. (2)).

Fig. (5)

- 2. Do not absolutely perform any work (such as clamping or acting as a stopper, etc.) in the rotary direction (Fig. (3)).
   3. To clamp, make sure to do so within the clamp stroke (straight-line stroke) range (Fig. (4)).
- 4. Make sure that the clamping surface of the workpiece is perpendicular to the cylinder's axial line (Fig. (5)).
- 5. Do not operate the cylinder in such a way that an external force causes the workpiece to move while being clamped (Fig. (6)).
- 6. Furthermore, do not operate the cylinder in an application in which a rotational force will be applied to the piston rod.



**SMC** 

Fig. (6)

REA

C

# Rotary Clamp Cylinder: Standard Type Series MK ø12, ø16, ø20, ø25, ø32, ø40, ø50, ø63

How to Order MK A 20 F9BW 10 R F S Number of auto switches Nil 2 pcs. Mounting style Auto switch S 1 pc. Symbol Mounting Applicable bore (mm) Without auto switch Nil (Built-in magnet) В Through-hole/Both ends tapped common (Standard 12, 16 \* For the applicable auto switch model, Α Both ends tapped style refer to the table below. В Through-hole 20 to 63 \* Auto switches are shipped together, G Head side flange style (but not assembled). \*The head side flange is equipped with a boss mounting, so be sure to specify body option "F". Body option Bore size Symbol Standard (Female thread) 12 mm 32 mm **Rotary direction** 12 32 М Rod end width across flats\* (Release  $\rightarrow$  Clamp) 16 40 16 mm 40 mm F With boss on head end\* 20 50 20 mm 50 mm R Clockwise Ν With arm 25 25 mm 63 63 mm L Counterclockwise Regarding manufacturable range of body option, refer to the table. Clamp stroke Manufacturable Range of Body Options Clamp stroke Applicable bore (mm) Symbol Bore size (mm) Nil М F Ν MF FN 10 10 mm 12 to 40 20 20 mm 12 to 63 12, 16 • 50 50 mm 50 to 63 20 to 63 0 • • •

#### Applicable Auto Switch/Refer to page 10-20-1 for further information on auto switches.

			Ħ			oad volta	ane	Rail mo	untina	Direct m	nountina	Lead v	wire le	enath	(m)*						
Туре	Special function	Electrical	torlig	Wiring			0	ø20 to		ø12, ø16, ø		0.5	3	. <u> </u>	None	Pre-wire		cable			
Type		entry	ndicator light	(Output)	D	C	AC	Perpendicular		Perpendicular	In-line	(Nil)		(Z)		connector	lo	ad			
_			_	3-wire (NPN equivalent)	-	5 V	_		A76H	A96V	A96	•	•	_	_	_	IC circuit	_			
Reed switch		Grommet			_	_	200 V	A72	A72H	_	—	•		—	_	_					
d sv	-		Yes				100.14	A73	A73H	-	—	•			_	—					
lee			$\succ$	2-wire	24 V	12 V	100 V	—	—	A93V	A93	•		—	_	—	—	Relay, PLC			
ш		Connector			24 V	12 V	—	A73C	—	_	—	•				—		PLC			
	Diagnostic indication (2-color indication)	Grommet				—	—	A79W	—	—	—	•		—		—					
				3-wire (NPN)				F7NV	F79	—	—		$\bullet$	0	_	0					
				5-wile (141 14)		5 V, 12 V	,	—	—	M9NV	M9N		$\bullet$	0	—	0	IC circuit				
		Grommot		3-wire (PNP)		J V, 12 V		F7PV F7P —	—			0	—	0							
	_	_ Grommet		3-WIE (FINF)				—	—	M9PV	M9P	•	$\bullet$	0	—	0					
						12 V		F7BV	J79	—	—		$\bullet$	0	—	0					
Solid state switch				2-wire			12 V	V	—	—	M9BV	M9B		$\bullet$	0	_	0				
świ		Connector							J79C	—	—	—					—				
te			Yes	3-wire (NPN)	24 V		_	F7NWV	F79W	—			$\bullet$	0	—	0	1	Relay,			
sta	Discussetia autout		×	S-WIE (INPIN)	24 V	5 V, 12 V		5 V, 12 V	5 V 12 V		—	—	F9NWV	F9NW		$\bullet$	0	—	0	IC circuit	PLC
plid	Diagnostic output (2-color indication)			3-wire (PNP)					V, 12 V			—	F7PW	—	—		$\bullet$	0	_	0	
S				0-wile (1 Wil)				—	—	F9PWV	F9PW		$\bullet$	0	—	0	1				
		Grommet						F7BWV	J79W	F9BWV	F9BW			0	—	0					
	Water resistant			2-wire		12 V	12 V	12 V	2 V		—	F7BA	-	F9BA	—	$\bullet$	0	—	0	_	
	(2-color indication)							F7BAV	—	—	—	_	$\bullet$	0	—	—					
	With diagnostic output (2-color indication)			4-wire (NPN)		5 V, 12 V		—	F79F	-	—	•	$\bullet$	0	—	0	IC circuit				
	Magnetic field resistant (2-color indication)			2-wire		—		—	P5DW	-	—	_			_	0	—				
* Lead	d wire length symb	3 n	n	L (Èx	ample) / ample) / ample) /	473CL								•		iced upon i izes ø40, ø	•				

None ········ N (Example) A73CN

\* D-P5DWL type can only be mounted for bore sizes ø40, ø50, ø63. \* Only D-P5DWL type is assembled at the time of shipment.

• Since there are other applicable auto switches than listed, refer to page 10-7-14 for details.

• For details about auto switches with pre-wire connector, refer to page 10-20-66.



## Rotary Clamp Cylinder: Standard Type Series MK





-XB6	Head resistant cylinder (150°C)

#### **Option Part No./Arm**

Bore size (mm)	Part no.	Accessory
12	MK-A012	
16	MK-A016	Clamp halt
20	MK-A020	Clamp bolt
25	WIK-AU2U	Hexagon socket head cap screw
32	MK-A032	Hexagon nut
40	IVIN-AU32	Spring washer
50	MK-A050	
63	WIX-A050	

#### **Mounting Bracket Part No./Flange**

Bore size (mm)	Part no.	Accessory
20	MK-F020	
25	MK-F025	Centering location ring
32	MK-F032	Set pin
40	MK-F040	Bolt for cylinder body
50	MK-F050	
63	MK-F063	

Specif	ications
--------	----------

Bo	re size (mm)	)	12	16	20	25	32	40	50	63	
Action		Double acting									
Rotary and				90° :	±10°						
Rotary dire	ection (2)			R: Clockwise, L: Counterclockwise							
Rotary stro	oke (mm)		7.5	5	9	.5	1	5	1	19	
Clamp stro	oke (mm)				10	, 20			20	, 50	
Allowable	moment (N-	·m) (3)	1	3.8	7	13	27	47	107	182	
Theoretica	al clamp forc	e (N) (4)	40	75	100	185	300	525	825	1400	
Fluid						A	ir				
Proof pres						1.5					
Operating	pressure ra	nge	-			0.1 to 1					
Ambient a	nd fluid tem	perature	•			witch: –1 itch: –10			0,		
Lubricatio	n					Non-	lube				
Piping por	t size				x 0.8		Ro	; <sup>1</sup> / <sub>8</sub>	Ro	c <sup>1</sup> / <sub>4</sub>	
Mounting			Through-h ends tapped	ole/Both common	Both er	nds tappe	d, Throu	gh-hole,	Head sic	le flange	
Cushion						Rubber					
Stroke len	gth toleranc	e				+0 -0	.6 .4				
Piston spe	ed					50 to 20	0 mm/s				
		.4° ±1.2° ±0.9°				±0.7°					
te 1) Refer t te 2) Directio te 3) Max. b te 4) At 0.5 I		e" figure. iewed fror it applied t				d retracting	-	9°	±C	).7°	
ote 1) Refer t ote 2) Directio ote 3) Max. b ote 4) At 0.5 I <b>heoret</b>	o "Rotary angle on of rotation vi ending momen MPa.	e" figure. iewed fror ti applied f	n the rod side o the piston r	od side.				-	1	).7° (N	
ote 1) Refer to the 2) Direction the 3) Max. b the 4) At 0.5 I <b>heoret</b> Bore size	o "Rotary angle on of rotation vi ending momen MPa. ical Out Rod size	e" figure. iewed fror it applied f <b>put</b> Operating	n the rod side o the piston r Piston area	a	e piston ro	Operatir		sure (MP	1	(N	
ote 1) Refer t ote 2) Directio ote 3) Max. b ote 4) At 0.5 I <b>heoret</b>	o "Rotary angle on of rotation vi ending momen MPa.	e" figure. iewed fror it applied f <b>put</b> Operating direction	n the rod side o the piston r Piston area (cm²)	a	e piston ro 0.3	Operatir 0.5		ure (MP	1	(N) 1.0	
ote 1) Refer to the 2) Direction the 3) Max. b the 4) At 0.5 I <b>heoret</b> Bore size	o "Rotary angle on of rotation vi ending momen MPa. ical Out Rod size	e" figure. iewed fror it applied f <b>put</b> Operating direction R	n the rod side o the piston r Piston are: (cm²) 0.8	a	e piston ro 0.3 24	Operatir 0.5 40		oure (MP 0.7 56	a)	(N 1.0 80	
te 1) Refer t te 2) Directid te 3) Max. b te 4) At 0.5 I heoret Bore size (mm)	o "Rotary angle on of rotation vi ending momen MPa. ical Out Rod size (mm)	e" figure. iewed fror it applied put Operating direction R H	n the rod side o the piston r Piston area (cm <sup>2</sup> ) 0.8 1.1	a	e piston ro 0.3 24 33	Operatir 0.5 40 55		ure (MP 0.7 56 77	a)	(N 1.0 80 110	
te 1) Refer t te 2) Directid te 3) Max. b te 4) At 0.5 I heoret Bore size (mm)	o "Rotary angle on of rotation vi ending momen MPa. ical Out Rod size (mm)	a" figure. iewed fror it applied to put Operating direction R H R	Piston area (cm <sup>2</sup> ) 0.8 1.1 1.5	a	e piston ro 0.3 24 33 45	Operatir 0.5 40 55 75		ure (MP 0.7 56 77 105	a)	(N 1.0 80 110 150	
te 1) Refer t tote 2) Direction te 3) Max. b tote 4) At 0.5 I heoret Bore size (mm) 12	o "Rotary angle on of rotation vi ending momen MPa. ical Out Rod size (mm) 6	a" figure. iewed fror it applied put Operating direction R H H H	Piston area (cm <sup>2</sup> ) 0.8 1.1 1.5 2	a	0.3 24 33 45 60	Operatir 0.5 40 55 75 100		ure (MP 0.7 56 77 105 140	a)	(N 1.0 80 110 150 200	
te 1) Refer t tote 2) Direction te 3) Max. b tote 4) At 0.5 I heoret Bore size (mm) 12	o "Rotary angle on of rotation vi ending momen MPa. ical Out Rod size (mm) 6	a" figure. iewed fror t applied <b>put</b> Operating direction R H H R H	Piston area (cm <sup>2</sup> ) 0.8 1.1 1.5 2 2	a	0.3 24 33 45 60 60.8	Operatir 0.5 40 55 75 100 100		ure (MP 0.7 56 77 105 140 139	a)	(N 1.0 80 110 150 200 200	
te 1) Refer t tote 2) Direction te 3) Max. b tote 4) At 0.5 I heoret Bore size (mm) 12 16	o "Rotary angle on of rotation vi ending moment MPa. iccal Out Rod size (mm) 6 8	a" figure. iewed fror it applied f <b>put</b> Operating direction R H H R H H	Piston area (cm <sup>2</sup> ) 0.8 1.1 1.5 2 2 3		0.3 24 33 45 60 60.8 90.2	Operatir 0.5 40 55 75 100 100 149		ure (MP 0.7 56 77 105 140 139 208	a)	(N 1.0 80 110 150 200 200 298	
te 1) Refer t tote 2) Direction te 3) Max. b tote 4) At 0.5 I heoret Bore size (mm) 12 16	o "Rotary angle on of rotation vi ending moment MPa. iccal Out Rod size (mm) 6 8	a" figure. iewed fror t applied f operating direction R H H R H R H R	Piston area (cm <sup>2</sup> ) 0.8 1.1 1.5 2 2 3 3.7		0.3 24 33 45 60 60.8 90.2 112	Operatir 0.5 40 55 75 100 100 149 185		ure (MP 0.7 56 77 105 140 139 208 258	a)	(N 1.0 80 110 150 200 200 298 370	
te 1) Refer t tote 2) Direction te 3) Max. b tote 4) At 0.5 I <b>heoret</b> Bore size (mm) 12 16 20	o "Rotary angle on of rotation vi ending moment MPa. ical Out Rod size (mm) 6 8 12	a" figure. iewed fror t applied f Operating direction R H H R H H R H H	Piston area (cm <sup>2</sup> ) 0.8 1.1 1.5 2 2 3 3.7 4.9		0.3 24 33 45 60 60.8 90.2 112 149	Operatir 0.5 40 55 75 100 100 149 185 245		ure (MP 0.7 56 77 105 140 139 208 258 341	a)	(N 1.0 80 110 150 200 200 298 370 490	
te 1) Refer t tote 2) Direction te 3) Max. b tote 4) At 0.5 I <b>heoret</b> Bore size (mm) 12 16 20	o "Rotary angle on of rotation vi ending moment MPa. ical Out Rod size (mm) 6 8 12	a" figure. iewed fror t applied to put Operating direction R H R H R H R H R H R H R	Piston area (cm <sup>2</sup> ) 0.8 1.1 1.5 2 2 3 3.7 4.9 6		e piston ro 0.3 24 33 45 60 60.8 90.2 112 149 182	Operatir 0.5 40 55 75 100 100 149 185 245 300		ure (MP 0.7 56 77 105 140 139 208 258 341 418	a)	(N 1.0 80 110 150 200 298 370 490 600	
te 1) Refer t te 2) Direction te 3) Max. b te 4) At 0.5 I heoret (mm) 12 16 20 25 32	o "Rotary angle on of rotation viending moment MPa. ical Out Rod size (mm) 6 8 12 12	a" figure. iewed fror t applied to put Operating direction R H R H R H R H R H H H H H	Piston area (cm <sup>2</sup> ) 0.8 1.1 1.5 2 2 3 3.7 4.9 6 8	a	e piston ro 0.3 24 33 45 60 60.8 90.2 112 149 182 243	Operatir 0.5 40 55 75 100 100 149 185 245 300 400		ure (MP 0.7 56 77 105 140 139 208 258 341 418 557	a)	(N 1.0 80 110 150 200 200 298 370 490 600 800	
te 1) Refer t te 2) Direction te 3) Max. b te 4) At 0.5 I heoret Bore size (mm) 12 16 20 25	o "Rotary angle on of rotation viending moment MPa. ical Out Rod size (mm) 6 8 12 12	a" figure. iewed fror t applied f put Operating direction R H R H R H R H R H R H R H R H R H R	Piston area (cm <sup>2</sup> ) 0.8 1.1 1.5 2 2 3 3.7 4.9 6 8 10.5	a	e piston ro 0.3 24 33 45 60 60.8 90.2 112 149 182 243 319	Operatir 0.5 40 55 75 100 100 149 185 245 300 400 525		ure (MP 0.7 56 77 105 140 139 208 258 341 418 557 731	a)	(N 1.0 80 110 150 200 200 298 370 490 600 800 050	
te 1) Refer t te 2) Direction te 3) Max. b te 4) At 0.5 I heoret Bore size (mm) 12 16 20 25 32 40	o "Rotary angle on of rotation viending moment MPa. <b>ical Out</b> Rod size (mm) 6 8 12 12 16	a" figure. iewed fror t applied to put Operating direction R H R H R H R H R H R H H H H H H H H H H H H H	Piston area (cm <sup>2</sup> ) 0.8 1.1 1.5 2 2 3 3.7 4.9 6 8 10.5 12.5	a	e piston ro 0.3 24 33 45 60 60.8 90.2 112 149 182 243 319 380	Operatir 0.5 75 100 100 149 185 245 300 400 525 625		ure (MP 0.7 56 77 105 140 139 208 258 341 418 557 731 870	a)	(N 80 110 150 200 200 298 370 490 600 800 050 250	
te 1) Refer t te 2) Direction te 3) Max. b te 4) At 0.5 I heoret Bore size (mm) 12 16 20 25 32	o "Rotary angle on of rotation viending moment MPa. <b>ical Out</b> Rod size (mm) 6 8 12 12 16	a" figure. iewed fror t applied to put Operating direction R H R R H R R H R R H R R R R R R R R R R R R R	Piston area (cm <sup>2</sup> ) 0.8 1.1 1.5 2 2 3 3.7 4.9 6 8 10.5 12.5 16.5	a	e piston ro 0.3 24 33 45 60 60.8 90.2 112 149 182 243 319 380 502	Operatir 0.5 75 100 100 149 185 245 300 400 525 625 825		ure (MP 0.7 56 77 105 140 139 208 258 341 418 557 731 870 1149	a)	(N 80 110 150 200 298 370 490 600 800 050 250 648	
te 1) Refer t tote 2) Direction te 3) Max. b tote 4) At 0.5 I <b>heoret</b> i Bore size (mm) 12 16 20 25 32 40 50	o "Rotary angle on of rotation viending momen MPa. <b>ical Out</b> Rod size (mm) 6 8 12 12 16 16	a" figure. iewed fror t applied to put Operating direction R H R H R H R H R H R H R H H R H H H H H H H H H H H H H	Piston area (cm <sup>2</sup> ) 0.8 1.1 1.5 2 2 3 3.7 4.9 6 8 10.5 12.5 16.5 19.6	a conside.	e piston ro 0.3 24 33 45 60 60.8 90.2 112 149 182 243 319 380 502 596	Operatir 0.5 75 100 100 149 185 245 300 400 525 625 825 825 980		ure (MP 0.7 56 77 105 140 139 208 258 341 418 557 731 870 1149 1365	a)	(N 80 110 150 200 200 298 370 490 600 800 050 250 648 961	
te 1) Refer t te 2) Direction te 3) Max. b te 4) At 0.5 I heoret Bore size (mm) 12 16 20 25 32 40	o "Rotary angle on of rotation viending momen MPa. <b>ical Out</b> Rod size (mm) 6 8 12 12 16 16	a" figure. iewed fror t applied to put Operating direction R H R R H R R H R R H R R R R R R R R R R R R R	Piston area (cm <sup>2</sup> ) 0.8 1.1 1.5 2 2 3 3.7 4.9 6 8 10.5 12.5 16.5	a	e piston ro 0.3 24 33 45 60 60.8 90.2 112 149 182 243 319 380 502	Operatir 0.5 75 100 100 149 185 245 300 400 525 625 825		ure (MP 0.7 56 77 105 140 139 208 258 341 418 557 731 870 1149	a)	(N 80 110 150 200 298 370 490 600 800 050 250 648	

#### Weight/Through-hole Mounting

Clamp stroke	Bore size (mm)									
(mm)	12	16	20	25	32	40	50	63		
10	70	100	250	280	500	595	_	—		
20	87	123	290	320	525	640	1100	1520		
50	—	_	—	—	—		1350	1805		

### Additional Weight

-

Additional Weight								(g)	-X
Bore size (mm)	12	16	20	25	32	40	50	63	
Both ends tapped style	—	—	6	7	7	6	7	17	20-
Rod end width across flats	—	—	10	10	21	21	46	46	
With boss in head side	—	—	2	3	5	7	13	25	Data
With arm	13	32	100	100	200	200	350	350	
Rear flange type (including mounting bolt)	—	—	133	153	166	198	345	531	
Calculation: (Example) MKG20-10R	FN •Stand	lard calcula	tion: N	IKB20-10R		250 g			

alculation: (Example) MKG20-10RFN

Extra weight calculation: Both ends tapped style

6 g Rear flange 133 g

With boss in head side 2 g

With arm 100 g 491 g

(g)

### Construction



### **Component Parts**

No.	Description	Material	Note		
1	Rod cover	Aluminum alloy	Hard anodized		
2	Cylinder tube	Aluminum alloy	Hard anodized		
3	Piston	Aluminum alloy			
4	Bushing	Copper bearing material	Only ø32 to ø63		
(5)	Guide pin	Stainless steel	Nitrided		
(6)	Piston rod	Stainless steel	ø12 to 25 Nitrided		
	FISIOITIOU	Carbon steel	ø32 to ø63 Heated, Nickel plated		
7	Bumper	Urethane			
8	Ring nut	Copper alloy	Only ø20 to ø32		
9	Scraper pressure	Stainless steel	Except ø12, ø16		
10	Rubber magnet	Synthetic rubber			
1	Hexagon socket head set screw	Chromium molybdenum steel	Sharp end section: 90°		
(12)	Round type R retainer	Spring steel			
(13)	Parallel pin	Stainless steel			

No.	Description	Material	Note
(14)	Type C snap ring	Carbon tool steel	Only ø40 to ø63
(15)	Arm	Rolled steel	
(16)	Clamp bolt	Chromium molybdenum steel	
17	Hexagon nut	Rolled steel	
(18)	Hexagon socket head cap screw	Chromium molybdenum steel	
(19)	Spring washer	Hard steel	
20	Centering location ring	Aluminum alloy	Except ø12, ø16
21)	Flange	Rolled steel	Except ø12, ø16
22	Hexagon socket	Chromium molybdenum	ø25, 25: 2
Ŵ	head cap screw	steel	Qty. Ø32 to 63: 4
23	Spacer for switch type	Aluminum alloy	Only ø12, ø16
24)	Coil scraper	Phosphor bronze	
25	Piston seal	NBR	
26	Gasket	NBR	
27	Rod seal	NBR	
28	O-ring	NBR	

### **Replacement Parts: Seal Kit**

Bore size (mm)	12	16	20 to 32	40	50	63				
Kit no.	MK-12-PS	MK-16-PS	Not able to disassemble	MK-40-PS	MK-50-PS	MK-63-PS				
Content		Set of nos. above 24 25 26 27 28								

\* Seal kit includes 2 to 2. (Except ø20 to ø32) Order the seal kit, based on each bore size.



## A Precautions

Be sure to read before handling. For Safety Instructions and Actuator Precautions, refer to pages 10-24-3 to I 10-24-6.

### A Caution

### **Mounting of Clamp Arm**

1. Use a clamp arm that is available as an option. To fabricate a clamp arm, make sure that the allowable bending moment and the inertial moment will be within the specified range. If a clamp arm that exceeds the specified value is installed, the internal mechanism in the cylinder could become damaged.

#### Ensuring Safety

1. If one side of the piston is pressurized by supplying air with the clamp arm attached, the piston will move vertically while the clamp arm rotates. This operation could be hazardous to personnel, as their hands or feet could get caught by the clamp arm, or could lead to equipment damage. Therefore, it is important to secure as a danger zone a cylindrical area with the length of the clamp arm as its radius, and the stroke plus 20 mm as its height.

#### Installation and Adjustment/Regarding Clamp Arm Removal and Reinstallation

1. During the removal or reinstallation of the clamp arm, make sure to use a wrench or a vise to secure the clamp arm before removing or tightening the bolt.

This is to prevent the bolt tightening torque from being applied to the piston rod, which could damage the cylinder's internal mechanism

#### Mounting bolt for MKB

Mounting method: Mounting bolt for through-hole type is available as an option. Ordering: Add the word "MKB" in front of the bolts to be used.

#### Example) M5 x 75ℓ (MKB)



Note) Be sure to use a flat washer to mount ø12 and ø16 cylinders via through-holes

Model	С	D	Mounting bolt
MKB12-10	8	50	M3 x 50ℓ
MKB12-20	8	60	M3 x 60ℓ
MKB16-10	8	50	M3 x 50ℓ
MKB16-20	8	60	M3 x 60ℓ
MKB20-10	10	75	M5 x 75ℓ
MKB20-20	10	85	M5 x 85ℓ
MKB25-10	9	75	M5 x 75ℓ
MKB25-20	9	85	M5 x 85ℓ
MKB32-10	10.5	85	M5 x 85ℓ
MKB32-20	10.5	95	M5 x 95ℓ
MKB40-10	7	75	M5 x 75ℓ
MKB40-20	/	85	M5 x 85ℓ
MKB50-20	6.5	95	M6 x 95ℓ
MKB50-50	11.5	130	M6 x 130ℓ
MKB63-20	10.5	100	M8 x 100ℓ
MKB63-50	10.5	130	M8 x 130ℓ

#### Precautions for Designing and Mounting Arms

When arms are to be made separately, their length and weight should be within the following range.

#### 1. Allowable bending moment

Use the arm length and operating pressure within graph (1) for allowable bending moment loaded piston rod.







	When arm length is 8 cm, pressure should be less than MK⊡20/25: 0.45 MPa
	MK 32/40: 0.55 MPa
NXXIX	MK□50/63: 0.8 MPa.
NN	
X	



MIs

CEP1

CE1

CE2

ML2B

C<sub>g</sub><sup>J</sup>5-S

CV

MVGQ

CC

RB

J

D-

-Х

20-

Data

REB

REC

C□X

#### 2. Moment of inertia

When the arm is long and heavy, damage of internal parts may be caused due to inertia. Use the inertia moment and cylinder speed within graph (2) based on arm requirements.

#### Graph (2)



To attach and detach the arm to and from the piston rod, fix the arm with a wrench or vise and then tighten the bolt.

(If an excessive force is applied in the rotary direction, it may bring about the damage to the internal mechanism.)

Refer to the following table for the tightening torque for mounting. (N.m)

	(1111)
Bore size (mm)	Proper tightening torque
12	0.4 to 0.6
16	2 to 2.4
20, 25	4 to 6
32, 40	8 to 10
50, 63	14 to 16

When arm's moment of inertia is 3 x 10<sup>-4</sup> kg·m<sup>2</sup>, cylinder speed should be less than MK□20/25: 65 mm/s MKD32/40: 150 mm/s For calculating moment of inertia, refer to page 10-7-21.







Note 1) Above figure is for D-A73/A80.

Note 2) Dimensions E and F are 7 mm longer for the auto switches with connector (D-A7 C/A80C/J79C).

Note 3) Dimension when the rod is extended is to be added to clamp stroke plus rotary stroke.





ø32, ø40, ø50, ø63

#### Through-hole (Basic style): MKB



#### Both ends tapped style: MKA



	(	mm)
Model	Α	В
MKA 32 40	M6 x 1.0	10
MKA50	M8 x 1.25	14
MKA63	M10 x 1.5	18

																							(mm)
Model	A	в	С	D	Е	F	G	н	I	J	к	L	0	Р	Q	R	S	т	U	V	x	Yh9	z
MKB32	45	60	34	<b>14</b> <sup>-0.1</sup> <sub>-0.2</sub>	54	31.5	5.5	9 depth 7	M10 x 1.5	12	20 <sup>±0.15</sup>	$7^{\pm 0.15}$	14	4.5	93.5	71.5	37	7.5	16	Rc <sup>1</sup> / <sub>8</sub>	3	30 _0_02	6.5
МКВ40	52	69	40	14 <sup>-0.1</sup> -0.2	61	35	5.5	9 depth 7	M10 x 1.5	12	24 <sup>±0.15</sup>	7 <sup>±0.15</sup>	14	5	94.5	65	29.5	8	16	Rc <sup>1</sup> / <sub>8</sub>	3	30 <sub>-0.062</sub>	6.5
MKB50	64	86	50	17 <sup>-0.1</sup> -0.2	73	41	6.6	11 depth 8	M12 x 1.75	15	$30^{\pm0.15}$	8 <sup>±0.15</sup>	19	7	112	76.5	34	10.5	20	Rc <sup>1</sup> / <sub>4</sub>	3.5	37 <sub>-0.062</sub>	7.5
MKB63	77	103	60	17 -0.1	86	47.5	9	14 depth 10.5	M12 x 1.75	15	$35^{\pm 0.15}$	9 <sup>±0.15</sup>	19	7	115	80	35	10.5	20	Rc <sup>1</sup> / <sub>4</sub>	3.5	48_0_02	7.5

Note 1) Above figure is for D-A73/A80. Note 2) Dimensions E and F are 7 mm longer for the auto switches with connector (D-A7⊡C/A80C/J79C). Note 3) Dimension when the rod is extended is to be added to clamp stroke plus rotary stroke.

## Rotary Clamp Cylinder: Standard Type Series MK

#### Head side flange style: MKG



With arm



Model	Α	В	С	D	F	G	н
MK□32-□□N	18	67	20	45	35.5	25	M8 x 1.25
MK□40-□□N	18	67	20	45	43	25	M8 x 1.25
MK□50-□□N	22	88	22	65	53	40	M10 x 1.5
MK 63-0 N	22	88	22	65	52.5	40	M10 x 1.5

With boss in head side



	(mm)
Model	Ah9
MK□32-□□F	21 _0_022
MK□40-□□F	28 <sub>-0.052</sub>
MK□ <sup>50</sup> -□□F	$35_{-0.062}^{0}$

#### Arm for width across flats

#### Rod end width across flats



							(mm)
Model	Α	В	С	D	Е	F	G
MK□32-□□M	6	14	53.5	36	18	9	6.2
MK□40-□□M	6	14	61	36	18	9	6.2
MK□50-□□M	8	18	77	46	23	11.5	8.2
MK□63-□□M	8	18	76.5	46	23	11.5	8.2

#### Mounting arms for width across flats



When installing the arm for the partiel section at the rod end, the strength of the piston rod might be insufficient depending on the direction in which the arm is installed. Therefore, make sure to install the arm in the direction indicated in figure A.

# Samp Cylinder: Standard Type **Series IVIN**

**SMC** 

REA REC C□X C□Y MQM RHC MK(2) RSGQ RS<sup>H</sup> RZQ MI<sub>s</sub> CEP1 CE1 CE2 ML2B C<sub>G</sub><sup>J</sup>5-S CV MVGQ CC RB J D--X 20-Data

### Proper Auto Switch Mounting Position (Detection at stroke end) and Its Mounting Height



Auto switch m	Auto switch model D-A9			I	D-A9⊡V	,	D-M9	)□, D-F	€⊐w	D-M9□V, D-F9□WV			
Symbol	A B W A B Hs		Hs	Α	В	W	Α	В	W				
Bore size	12	7.5	0	1.5 (4)	7.5	0	17	11.5	4.5	5.5	11.5	4.5	19.5
(mm)	16	8	0	2 (4.5)	8	0	19	12	4	6	12	4	21.5

Auto switch m	odel	D-F9BAL							
Symbol		Α	В	W	Hs				
Bore size	12	10.5	3.5	14.5	17				
(mm)	16	11	3	15	19				

\* ( ): Denotes the values of D-A93.

### Proper Auto Switch Mounting Position (Detection at stroke end)



														(mm)
Mounting			F	Rail mo	ounting	g style			Direct mounting style					
Model	D-A	7/A8	D-A7 D-A73C D-F7 D-F7 D-F7 D-F7BA D-J79W/	/A80C F79F/J79 V/J79C ⊐/F7⊡W	D-A	D-A79W D-P5DWL		/L D-A9□ D-A9□\		D-A9 D-M9 D-M9 V D-A9 V D-A9 V VD-F9 W		D-F9	BAL	
	Α	В	Α	В	Α	В	Α	В	Α	В	Α	В	Α	В
MK□20	28	6.5	28	7	25.5	4	_	—	—	_	_	_	_	_
MK□25	28.5	7	29	7.5	26	4.5	_	_	_	_	_	_		—
MK□32	32.5	6	33	6.5	30	3.5	_	—	31.5	5	35.5	9	34.5	8
MK□40	23.5	8.5	24	9	21	6	19.5	4.5	22.5	7.5	26.5	11.5	25.5	10.5
MK□50	28	11.5	28.5	12	25.5	9	24	7.5	27	10.5	31	14.5	30	13.5
MK□63	28	14.5	28.5	15	25.5	13	24	10.5	27	13.5	31	17.5	30	16.5

#### Auto Switch Mounting Bracket Part No.

Bore size	Mounting bracket	Note	Applicable auto switch						
(mm)	part no.	NOLE	Reed switch	Solid state switch					
<b>20</b> , <b>25</b>	BQ-1	<ul> <li>Switch mounting screw (M3 x 0.5 x 8/)</li> <li>Square nut</li> </ul>	D-A7/A8	D-F7□/J79 D-F7□V					
32, 40 50, 63	<b>32</b> , <b>40 BQ-2</b> • Switch mounting screw (M3 x 0.5 x 10/)		D-A73C/A80C D-A7⊡H/A80H D-A79W	D-J79C D-F7□W/J79W D-F7□WV D-F7BAL/F7BAVL D-F79F D-F7NTL					
40, 50 63	BQP1-050	<ul> <li>Switch mounting bracket</li> <li>Switch mounting nut</li> <li>Round head Phillips screw (M3 x 0.5 x 16t)</li> <li>Hexagon socket head cap bolt (M3 x 0.5 x 14t)</li> </ul>	_	D-P5DWL					

Precautions Be sure to read before handling. For Safety Instructions and Actuator Precautions, I refer to pages 10-24-3 to 10-24-6. Mounting

As shown in the figure below, when a magnetic body is in close contact with the cylinder body periphery (including the case where only one side is in contact), the function of the auto switch may be unstable. Please contact SMC if this occurs.





Magnetic body (Steel plate, etc.)

MIs CEP1 CE1 CE2 ML2B C<sub>G</sub><sup>J</sup>5-S CV

REB

REC

C

C□Y

MQM

RHC

MK(2)

RSGQ

RS<sup>H</sup>

RZQ

-Х

20-

Data

Mounting screws	set made of	f stainless steel	
<b>T</b> I I C I I I		/	

The set of stainless steel mounting screws (with nuts) described below is available and can be used depending on the operating environment. (Please order the auto switch spacer, since it is not included.)

BBA2: For D-A7/A8/F7/J7

"D-F7BAL/F7BAVL" switch is set on the cylinder with the stainless steel screws above when shipped. When the switches are shipped as individual parts, the BBA2 is included.

### **Operating Range**

#### (*l* dimensions)

Auto switch model			В	ore si	ze (mr	n)		
Auto switch model	12	16	20	25	32	40	50	63
D-A7□/A80 D-A7H/A80H D-A73C/A80C	_	_	12	12	12	11	10	12
D-A79W	—	—	13	13	13	14	14	16
D-A9□/A9□V	6	7.5	—	—	9.5	9.5	9.5	11.5
D-F7□/J79 D-F7□V/J79C D-F7□W/F7□WV/J79W D-F79F/F7BAL/F7BAVL/F7NTL	_		5.5	5	6	6	6	6.5
D-M9□/M9□V	2	2.5	—	—	4.5	4	4.5	5
D-F9□W/F9□WV D-F9BAL	3	4	_	_	5.5	5.5	5.5	6
D-P5DWL			—		—	5	5	5

\* Since this is a guideline including hysteresis, not meant to be guaranteed. (Assuming approximately ±30% dispersion.)

There may be varied substantially depending on the surrounding environment.

Other than the models listed in "How to Order", the following auto switches are applicable.

Туре	Model	Electrical entry (Fetching direction)	Features	Applicable bore size (mm)			
	D-A80	Grommet (Perpendicular)					
	D-A80H	Grommet (In-line)	Without	20 to 63			
Reed	D-A80C	Connector (Perpendicular)	indicator				
switch	D-A90	Grommet (In-line)	light	12, 16			
	D-A90V	Grommet (Perpendicular)		32 to 63			
Solid state switch D-F7NTL Grommet (In-line) With timer 20 to 63							
Witch     Witch     Witch     Witch     Witch     Witch     Witch     Work     Work							

Normally closed (NC = b contact), solid state switch (D-F9G/F9F I. type) are also available. For details, refer to page 10-20-40.





#### Applicable Auto Switch/Refer to page 10-20-1 for further information on auto switches.

			light		L	oad volta	ige	Rail mo	ounting	Direct m	nounting	Lead v	vire le	ength	n (m)*	_			
Туре	Special function	Electrical	Indicator light	Wiring (Output)	_	<u> </u>		ø20 to	o ø63	ø12, ø16, ø	ø32 to ø63	0.5	3	5	None	Pre-wire	Applica	able load	
		entry	Indic	(Output)	ט	c	AC	Perpendicular	In-line	Perpendicular	In-line	(Nil)	(L)	(Z)	(N)	connector			
ح				3-wire (NPN equivalent)	_	5 V	—	_	A76H	A96V	A96	•	•	_	—	_	IC circuit	_	
Reed switch		Grommet					200 V	A72	A72H	—	_		$\bullet$	—	—	—			
s S	—		Yes			1011	10011	A73	A73H		_				_	_		<b>_</b> .	
ee			≻	2-wire	24 V	12 V	100 V	—	—	A93V	A93			—	—	—	] —	Relay, PLC	
£		Connector			24 V	12 V	—	A73C	—	-	—				•	_		PLC	
	Diagnostic indication (2-color indication)	Grommet				_	—	A79W	—	—	—			—	—	—			
				3-wire (NPN)				F7NV	F79	_	—			0	_	0			
				S-WILE (INFIN)		5 V, 12 V		—	—	M9NV	M9N			0	—	0	IC circuit		
		Grommet		3-wire (PNP)				F7PV	F7P	_	—			0	—	0		L	
	—	Giommet				1			—	—	M9PV	M9P			0	—	0		
				2-wire	12 V				F7BV	J79	—	—			0	—	0		
C-							12 V		—	—	M9BV	M9B		۲	0	—	0		
swit		Connector						J79C	—	—	—					—			
Solid state switch			Yes		24 V			F7NWV	F79W	—	—			0	—	0		Relay,	
sta	Dia mantina antara t		≫	3-wire (NPN)		EV 10V		—	—	F9NWV	F9NW			0	—	0	IC circuit	PLC	
lic	Diagnostic output			3-wire (PNP)		5 V, 12 V		—	F7PW	—	_			0	—	0		L	
So	(2-color indication)			5-wile (1 N1 )				—	—	F9PWV	F9PW			0	—	0			
		Grommet						F7BWV	J79W	F9BWV	F9BW			0	—	0			
	Water resistant			2-wire		12 V		—	F7BA	—	F9BA	—		0	—	0	—		
	(2-color indication)							F7BAV	—	—	—	—		0	—	—			
	With diagnostic output (2-color indication)			4-wire (NPN)		5 V, 12 V		—	F79F	—	—			0	—	0	IC circuit	t	
	Magnetic field resistant (2-color indication)			2-wire		—		—	P5DW	—	_	—	$\bullet$	lacksquare	—	0	—		
* Lead	d wire length syml	3	m۰۰	L (Ex	ample) ample) ample)	A73CL								•		ced upon r izes ø40, ø	•		

None·······N (Example) A73CN

\* Only D-P5DWL type is assembled at the time of shipment.

• Since there are other applicable auto switches than listed, refer to page 10-7-20 for details.

• For details about auto switches with pre-wire connector, refer to page 10-20-66.



## Rotary Clamp Cylinder: Heavy Duty Type Series MK2



Bore size (mm)	20	25	32	40	50	63	
Action			Double	e acting			
Rotary angle (1)		90° ±10°					
Rotary direction (2)		R: Clockwise, L: Counterclockwise					
Rotary stroke (mm)	9	.5	1:	5	1	9	
Clamp stroke (mm)		10	, 20		20	, 50	
Allowable moment (N·m) (3)	7	13	27	47	107	182	
Theoretical clamp force (N) (4)	100	185	300	525	825	1400	
Fluid	Air						
Proof pressure	1.5 MPa						
Operating pressure range	0.1 to 10 MPa						
Ambient and fluid temperature	Without auto switch: -10 to 70°C (No freezing)				g)		
Ambient and huid temperature	With auto switch: -10 to 60°C (No freezing)						
Lubrication			Non	-lube			
Piping port size	M5 x	x 0.8	Rc <sup>1</sup> / <sub>8</sub>		Rc <sup>1</sup> / <sub>4</sub>		
Mounting	Throu	gh-hole/Bo	th ends tapp	ed commo	n, Head sid	le flange	
Cushion			Rubber	bumper			
Stroke length tolerance				0.6 0.4			
Piston speed			50 to 20	00 mm/s			
Non-rotating accuracy	±1	.2°	±0.	9°	±C	).7°	
Note 1) Refer to "Rotary Angle" ( Note 2) Direction of rotation view Note 3) Max. bending moment a Note 4) At 0.5 MPa.	ved from th			ton rod is r	etracting.		
Theoretical Output							
Bore size Rod size Operating			Oporati	ng pressur			

### **Rotary Angle**



#### т

meoreu							(N)
Bore size (mm)	Rod size (mm)	Operating direction	Piston area (cm²)	0.3	Operating pro	essure (MPa) 0.7	1.0
(((((((((((((((((((((((((((((((((((((((	(((((((((((((((((((((((((((((((((((((((		. ,				-
20	12	R	2	60.8	100	139	200
		н	3	90.2	149	208	298
25	12	R	3.7	112	185	258	370
23	12	н	4.9	149	245	341	490
32	16	R	6	182	300	418	600
32	10	н	8	243	400	557	800
40	16	R	10.5	319	525	731	1050
40	10	н	12.5	380	625	870	1250
50	20	R	16.5	502	825	1149	1648
50	20	н	19.6	596	980	1365	1961
63	20	R	28	851	1400	1950	2801
03	20	н	31.2	948	1560	2172	3121

Note) Theoretical output (N) = Pressure (MPa) x Piston area (cm<sup>2</sup>) x 100 Operating direction R: Rod side (Clamp)

H: Head side (Release)

(g)

### **Option Part No./Arm**

Bore size (mm)	Part no.	Accessory
20	MK-A020	Claren halt
25	WIK-AU20	Clamp bolt
32		Hexagon socket head cap screw
40	MK-A032	Hexagon nut
50	MK-A050	Spring washer
63	WIX-A050	Opining Washer

#### Mounting Bracket Part No./Flange

Bore size (mm)	Part no.	Accessory
20	MK2-F020	
25	MK2-F025	Centering location ring
32	MK2-F032	Set pin
40	MK2-F040	Bolt for cylinder body
50	MK2-F050	
63	MK2-F063	

#### Weight/Mounting

Clamp stroke		Bore size (mm)					
(mm)	20	25	32	40	50	63	
10	260	295	353	635	—	_	
20	300	335	555	680	1170	1620	
50	—	—	_	—	1420	1890	

### Additional Weight

Additional Weight						(g)	
Bore size (mm)	20	25	32	40	50	63	
With boss in head side	2	3	5	7	13	25	
With arm	100	100	200	200	350	350	
Rear flange style (including mounting bolt)	133	153	166	198	345	531	
Calculation: (Example) MK2G20-10		Standard Extra wei			MK2B20 Rear flan With bos With arm	ige s in head	l side

260 g 133 g 2 g

100 g 495 g



## Construction



#### **Component Parts**

No.	Description	Material	Note
1	Rod cover	Aluminum alloy	
2	Cylinder tube	Aluminum alloy	
3	Piston	Aluminum alloy	
4	Bushing	Copper bearing material	Only ø32 to ø63
(5)	Guide pin	Stainless steel	Nitrided
6	Piston rod	Stainless steel	Nitrided
$\overline{O}$	Bumper	Urethane	
8	Ring nut	Copper alloy	Only ø20 to ø32
9	Scraper pressure	Stainless steel	
10	Magnet		
1	Hexagon socket head set screw	Chromium molybdenum steel	Sharp end section: 90°
(12)	Round R type retainer	Spring steel	
13	Name plate	Aluminum	
14)	Type C snap ring	Carbon tool steel	Only ø40 to ø63
(15)	Arm	Rolled steel	
16	Clamp bolt	Chromium molybdenum steel	

No.	Description	Material		Note
17	Hexagon nut	Rolled steel		
18	Hexagon socket head cap screw	Chromium molybdenum steel		
(19)	Spring washer	Hard steel		
20	Centering location ring	Aluminum alloy		
21)	Flange	Rolled steel		
22	Hexagon socket	Chromium molybdenum	Qty.	ø20, 25: 2
W	head cap screw	steel	Qiy.	ø32 to 63: 4
23	O-ring	NBR		
24)	Coil scraper	Phosphor bronze		
25	Piston seal	NBR		
26	Gasket	NBR		
27	Rod seal	NBR		
28	Parallel pin	Stainless steel		
29	Wear ring	Resin		
30	Bumper B	Urethane		

28

### **Replacement Parts: Seal Kit**

Bore size (mm)	20	25	32	40	50	63
Kit no.	Not	able to disasser	nble	MK2-40-PS	MK2-50-PS	MK2-63-PS
Content		5	Set of nos. above	3 24 25 26 27	)	

\* Seal kit includes 23 to 27. Order the seal kit, based on each bore size.



## A Precautions

Be sure to read before handling. For Safety Instructions and Actuator Precautions, refer to pages 10-24-3 to 10-24-6.

### Caution

#### Mounting of Clamp Arm

1. Use a clamp arm that is available as an option. To fabricate a clamp arm, make sure that the allowable bending moment and the inertial moment will be within the specified range. If a clamp arm that exceeds the specified value is installed, the internal mechanism in the cylinder could become damaged.

#### **Ensuring Safety**

1. If one side of the piston is pressurized by supplying air with the clamp arm attached, the piston will move vertically while the clamp arm rotates. This operation could be hazardous to personnel, as their hands or feet could get caught by the clamp arm, or could lead to equipment damage. Therefore, it is important to secure as a danger zone a cylindrical area with the length of the clamp arm as its radius, and the stroke plus 20 mm as its height.

#### Installation and Adjustment/Regarding **Clamp Arm Removal and Reinstallation**

1. During the removal or reinstallation of the clamp arm, make sure to use a wrench or a vise to secure the clamp arm before removing or tightening the bolt.

This is to prevent the bolt tightening torque from being applied to the piston rod, which could damage the cylinder's internal mechanism.

#### Mounting bolt for MK2B

Mounting method: Mounting bolt for through-hole type is available as an option. Ordering: Add the word "MK2B" in front of the bolts to be used.

Example) M5 x 75ℓ (MK2B)



Note) Be sure to use a flat washer to mount cylinders via through-holes

Model	С	D	Mounting bolt
MK2B20-10	8.5	75	M5 x 75ℓ
MK2B20-20	8.5	85	M5 x 85ℓ
MK2B25-10	10.5	80	M5 X 80 <i>ℓ</i>
MK2B25-20	10.5	90	M5 x 90ℓ
MK2B32-10	10	90	M5 x 90ℓ
MK2B32-20	10	100	M5 x 100 <i>t</i>
MK2B40-10	6	80	M5 x 80ℓ
MK2B40-20	0	90	M5 x 90ℓ
MK2B50-20	10.5	105	M6 x 105ℓ
MK2B50-50	10.5	135	M6 x 135ℓ
MK2B63-20	9	105	M8 x 105ℓ
MK2B63-50		135	M8 x 135ℓ

### Precautions for Designing and Mounting Arms

When arms are to be made separately, their length and weight should be within the following range.

#### 1. Allowable bending moment

Use the arm length and operating pressure within graph (1) for allowable bending moment loaded piston rod.









REA

REC

C□X

C□Y

MQM

RHC

MK(2)

RSG

RS<sup>H</sup>

RZQ

MIs

CEP1

CE1

CE2

ML2B

C<sub>g</sub><sup>J</sup>5-S

CV

MVGQ

CC

RB

J

D-

-X

20-

Data



#### 2. Moment of inertia

When the arm is long and heavy, damage of internal parts may be caused due to inertia. Use the inertia moment and cylinder speed within graph (2) based on armrequirements.



Graph (1)



When arm's moment of inertia is 5 x 10-3 kg.m<sup>2</sup>, cylinder speed should be less than MK2 $\square$ 32/40: 66 mm/s MK2 $\square$ 50/63: 120 mm/s.

For calculating moment of inertia, refer to page 10-7-21.



(If an excessive force is applied in the rotary direction, it may bring about the damage to the internal mechanism.)

Refer to the following table for the tightening toraue for mountina. (N.m)

(1111)
Proper tightening torque
4 to 6
8 to 10
14 to 16

**SMC** 







#### Through-hole/Both Ends Tapped Common (Standard) (mm)

Model		в	С	D	Е	F	G	øHh9	Т	ſ	к	L
MK2B20	36	46.8	36	48	24.5	13.5 ±0.15	7.5 ±0.15	20 _0_0	75.5	62.5	31	4
MK2B25	40	52	40	53.8	27.5	16 ±0.15	8 ±0.15	23 <sup>0</sup> 0.052	78.5	65.5	32	5

Note 1) Above figure is for D-A73/A80.
Note 2) Dimensions E and F are 7 mm longer for the auto switches with connector (D-A7□C/A80C/J79C).
Note 3) Dimension when the rod is extended is to be added to clamp stroke provide stroke. plus rotary stroke.

## Rotary Clamp Cylinder: Heavy Duty Type Series MK2

#### ø32, ø40, ø50, ø63



#### Through-hole/Both Ends Tapped Common (Standard)

	-						-																		,		00
	Model		в	С	D	Е	F	øG	øH	I	J	к	L	м	Ν	0	Ρ	Q	R	s	т	øU	٧	X	øYh9	z	20-
	MK2B32	45	60	34	<b>14</b> <sup>-0.1</sup> -0.2	54	31.5	5.5	9 depth 7	M10 x 1.5	12	20 ±0.15	7 ±0.15	M6 x 1.0	17	14	4.5	101.5	76	37	7.5	16	Rc 1/8	3	30_0_0_2	6.5	Data
Į	MK2B40	52	69	40	<b>14</b> <sup>-0.1</sup> -0.2	61	35	5.5	9 depth 7	M10 x 1.5	12	24 ±0.15	7 ±0.15	M6 x 1.0	17	14	5	102.5	70	29.5	8	16	Rc 1/8	3	30 <sub>-0.062</sub>	6.5	Data
	MK2B50	64	86	50	17 <sup>-0.1</sup> -0.2	73	41	6.6	11 depth 8	M12 x 1.75	15	$30 \ ^{\pm 0.15}$	8 ±0.15	M8 x 1.25	22	19	7	122	81.5	34	10.5	20	Rc 1⁄4	3.5	37 <sub>-0.062</sub>	7.5	
	MK2B63	77	103	60	<b>17</b> <sup>-0.1</sup> <sub>-0.2</sub>	86	47.5	9	14 depth 10.5	M12 x 1.75	15	$35 \ ^{\pm 0.15}$	<b>9</b> ±0.15	M10 x 1.5	28.5	19	7	125	85	35	10.5	20	Rc 1⁄4	3.5	$48_{-0.062}^{0}$	7.5	

Note 1) This cylinder rod is retracted.

Note 2) Rotary direction is viewed from the rod side when the piston rod is retracting.

Note 3) Dimension when the rod is extended is to be added to clamp stroke plus rotary stroke.

10-7-19



(mm)

REA

REC

C□X

C□Y

MQM

RHC

MK(2)

RSGQ

RS<sup>H</sup>

RZQ

MI<sub>s</sub><sup>w</sup>

CEP1

CE1

CE2

ML2B

C<sub>G</sub><sup>J</sup>5-S

CV

MVGQ

CC

RB

J

D-

### Proper Auto Switch Mounting Position (Detection at stroke end)



Mounting	Rail mounting style										Direct	mounting	style	
Model	D-A7/A8		D-F7BAC/F7CW D-J79W/F7CWV			79W	D-P5	DWL	D-A9⊡ D-A9⊡V		D-M9□ D-M9□V D-F9□W D-F9□WV		D-F9BAL	
	A	В	A	В	Α	В	Α	В	Α	В	Α	В	Α	В
MK2□20	28.5	6	29	6.5	26	3.5	_	—	_	—	_	—		_
MK2□25	29	6.5	29.5	7	26.5	4	—	—	_	—	—	—	—	—
MK2□32	32.5	10.5	33	11	30	8	_	_	31.5	9.5	35.5	13.5	34.5	12.5
MK2□40	23.5	13.5	24	14	21	11	19.5	9.5	22.5	12.5	26.5	16.5	25.5	15.5
MK2□50	28	16.5	28.5	17	25.5	14	24	12.5	27	15.5	31	19.5	30	18.5
MK2□63	28.5	19.5	29	20	26	17	24.5	15.5	27.5	18.5	31.5	22.5	30.5	21.5

#### Auto Switch Mounting Bracket Part No.

Bore size	Mounting bracket	Note	Applicable	auto switch
(mm)	part no.	Note	Reed switch	Solid state switch
20, 25	BQ-1	<ul> <li>Switch mounting screw (M3 x 0.5 x 8<i>t</i>)</li> <li>Square nut</li> </ul>	D-A7/A8 D-A73C/A80C	D-F7□/J79, D-F7□V, D-J79C
32, 40 50, 63	BQ-2	<ul> <li>Switch mounting screw (M3 x 0.5 x 10/)</li> <li>Switch spacer</li> <li>Switch mounting nut</li> </ul>	D-A73C/A80C D-A7⊡H/A80H D-A79W	D-F7□W/J79W/D-F7□WV D-F7BAL, D-F7BAVL, D-F79F, D-F7NTL
40, 50 63	BQP1-050	<ul> <li>Switch mounting bracket</li> <li>Auto switch mounting nut</li> <li>Round head Phillips screw (M3 x 0.5 x 16<i>i</i>)</li> <li>Hexagon socket head cap bolt (M3 x 0.5 x 14<i>i</i>)</li> </ul>	_	D-P5DWL

Mounting screws set made of stainless steel

The set of stainless steel mounting screws (with nuts) described below is available and can be used depending on the operating environment. (Please order the auto switch spacer, since it is not included.)

BBA2: For D-A7/A8/F7/J7

"D-F7BAL/F7BAVL" switch is set on the cylinder with the stainless steel screws above when shipped.

When only a switch is shipped independently, "BBA2" screws are attached.

### **Operating Range**

#### **Operating Range (Dimension)**

Auto switch model		В	ore siz	ze (mn	n)	
Auto switch model	20	25	32	40	50	63
D-A7□/A80 D-A7H/A80H D-A73C/A80C	12	12	12	11	10	12
D-A79□W	13	13	13	14	14	16
D-A9□/A9□V	_		9.5	9.5	9.5	11.5
D-F7=/J79 D-F7=V/F79F/J79C D-F7=W/F7=WV D-F79F/F7BAL/F7BAVL/F7NTL	5.5	5	6	6	6	6.5
D-M9□/M9□V	—	_	4.5	4.5	5	5
D-F9□W/F9□WV D-F9BAL	—	_	5.5	5.5	5.5	6
D-P5DWL	—	—	—	5	5	5

\* Since this is a guideline including hysteresis, not meant to be guaranteed. (Assuming approximately ±30% dispersion.) There may be the case it will vary substantially depending on an ambient environment.

Туре	Model	Electrical entry (Fetching direction)	Features	Applicable bore size (mm)
	D-A80	Grommet (Perpendicular)		. ,
	D-A80H	Grommet (In-line)	Without	20 to 63
Reed	D-A80C	Connector (Perpendicular)	indicator	
switch	D-A90	Grommet (In-line)	light	12, 16
	D-A90V	Grommet (Perpendicular)	-	32 to 63
Solid state switch	D-F7NTL	Grommet (In-line)	With timer	20 to 63



### **Caution on Handling**

### **▲** Caution

Be sure to read before handling. For Auto Switch Precautions, refer to pages 10-20-4 to 10-20-6.

## Magnetic field resistant auto switch resistant auto switch D-P5DWL

If welding cables or welding gun electrodes are in the vicinity of the cylinder, the magnets in the cylinder could be affected by the external magnetic fields. (Please contact SMC if the welding amperage exceeds 20,000 A.) If the source of strong magnetism comes in contact with the cylinder or an auto switch, make sure to install the cylinder away from the source of the magnetism. If the cylinder is to be used in an environment in which spatter will come in direct contact with the lead wires, cover the lead wires with a protective tube. For the protective tube, use a tube with a

bore of ø7 or more, which excels in heat resistance and flexibility. Please contact SMC if an inverter welder or a DC welder will be used.

I: Moment of Inertia (kg·m<sup>2</sup>) m: Load weight (kg)

### **Calculation for Moment of Inertia**

#### 1. Thin bar

Position of rotary axis: Vertical to the bar and through the end



### 2. Thin bar

Position of rotary axis: Vertical to the bar and through the center of gravity





3. Thin rectangular plate (Rectangular parallelepiped) Position of rotary axis: Parallel to side b and through the center of gravity





4. Thin rectangular plate (Rectangular parallelepiped)





 $\mathbf{I} = \mathbf{m}_1 \cdot \frac{4a_{1^2} + b^2}{12} + \mathbf{m}_2 \cdot \frac{4a_{2^2} + b^2}{12}$ 





#### 6. Load at the end of lever arm







REA

REC

C

C□Y

MQM

RHC

MK(2)

RSG

RS<sup>H</sup>

RZQ

MIs

CEP1

CE1

CE2

ML2B

C<sub>g</sub><sup>J</sup>5-S

CV

Data

# Product Profile: Clamp Cylinders

#### Clamp cylinder Series CK1/CKS1 Series CK1

Two sizes of clevis width (16.5 mm and 19.5 mm)

#### Series CKS1

(With magnetic field resistant auto switch) It is not affected by strong magnetic fields due to the adoption of an optical sensor switch.



Series CK1

Series CKS1

## Clamp cylinder with lock *Series CLK1*

Maintains a clamped or unclamped state when air supply pressure drops or residual pressure is released.

Since it can be locked at any position, it can deal with freely the changes of thickness of a workpiece.



Series CLK1



With magnetic field resistant auto switch Series CLK1G

Series	Type	Width o	of clevis	Bore size	Standard stroke	Speed	Mounting	Option	
Cenes	Type	16.5	16.5 19.5		(mm)	controller	style	Option	
				40	50, 75			<u>.</u>	
CK1	Standard	CK1A	CK1B	50	100, 125 150			Single knuckle joint	
				63		Built-in	Double	Double knuckle joint (With pin)	
	Magnetic			40	50, 75	Dunt in	clevis	Dog for limit switch	
CKS1	field resistant	CKS1A	CKS1B	50	100, 125			Dog fitting	
	auto switch			63	150				

Series	Туре	Bore size (mm)	Standard stroke (mm)	Mounting style	Locking method	Option
		32	50.75			
CLK1	Standard	40	50, 75 100, 125			Single knuckle joint
CLKI	Stanuaru	50	150	<b>D</b> 11	<b>o</b> .	Double knuckle joint
		63	100	Double clevis	Spring rod	(with pin)
	With magnetic	40	50, 75	00013	100	Dog for limit switch
CLK1G	field resistant	50	100, 125			Dog fitting
	auto switch	63	150			