# **Cylinder with Lock**

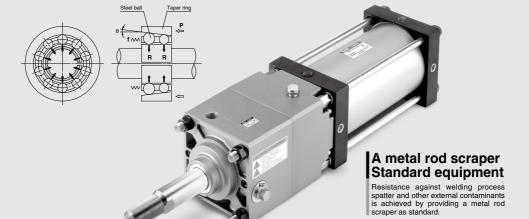
# **CNS** Series

ø125, ø140, ø160

# A locking cylinder ideal for intermediate stops, emergency stops and drop prevention.

# Simple construction

A force magnifying mechanism is employed based on the wedge effect of the taper ring and steel balls.



# High locking efficiency

Greater locking efficiency as well as stable locking and unlocking operation has been achieved by arranging a large number of steel ball bearings in circular rows. (Unlocking pressure of 0.25 MPa ..... 0.05 MPa lower than current SMC products) In addition, both alignability and stable locking force with respect to piston rod eccentricity are obtained by allowing the taper ring to float.

# High reliability and stable holding force

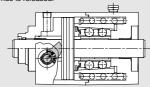
Outstanding durability and stable holding force are maintained by the use of a brake shoe having superior wear resistance, which has also been substantially lengthened (double the current SMC product).

### ■ Series Variations

_ 0000	· uu.					
Series	Action	Туре	Standard variations With rod boot	Bore size (mm)	Lock holding force (kN)	Standard stroke (mm)
	9 D	Cinala vad		125	8.4	M
Cylinder with lock	Double	Single rod CNS series	→-	140	10.5	Maximum 1600
	a D			160	13.8	1600

# Manual override for unlocking for emergency

Even if the air supply is blocked or exhausted, lock release is possible. The fail safe mechanism locks again when the manual override is released.



# Design minimizes the influences of unlocking air quality

A construction which is strong against moisture and drainage in the compressed air has been realized by separating the locking mechanism and the unlocking chamber.

# Can be locked in both directions

All equal holding force can be obtained on either reciprocating stroke of the cylinder.



# **Model Selection**

# **Precautions on Model Selection**

# **.** Caution

- 1. In order that the originally selected maximum speed is not exceeded, be certain to use a speed controller to adjust the total movement distance of the load so that movement takes place in no less than the applicable movement time. The movement time is the time that is necessary for the load
  - The movement time is the time that is necessary for the load to travel the total movement distance from the start without any intermediate stops.
- In cases where the cylinder stroke and the movement distance of the load are different (double speed mechanism, etc.), use the movement distance of the load for selection purposes.

# Movement distance of load

3. The following selection example and procedures are based on use at the intermediate stop (including emergency stops during the operation). However, when the cylinder is in the locked state, kinetic energy does not act upon it. Under these conditions, use the load mass at the maximum speed (V) of 100 mm/s shown in graphs 5 to 7 on page 797 depending on the operating pressure and select models.

# Selection Example

• Load mass: **m** = 320 kg • Movement distance: **st** = 400 mm

• Movement time: t = 2 s

Load condition:
 Vertical downward = Load in direction of rod extension

• Operating pressure: **P** = 0.4 MPa

Step (1): From graph (1) find the maximum movement speed of the load

∴ Maximum speed V: ≅ 280 mm/s

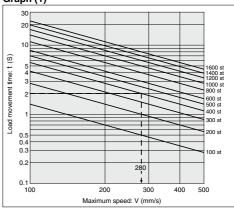
Step (2): Select Graph(6) based upon the load condition and operating pressure, and then from the intersection of the maximum speed V=280 mm/s found in Step (1), and the load mass  $m=320~{\rm kg}$ 

∴ Ø140 → select a CNS140 or larger bore size.

# Step 1 Find the maximum load speed V.

Find the maximum load speed: V (mm/s) from the load movement time: t (s) and the movement distance: st (mm).

# Graph (1)

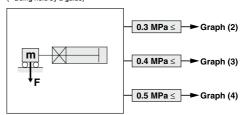


# Step 2 Find the bore size.

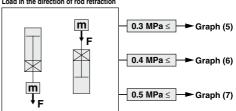
Select a graph based upon the load condition and operating pressure, and then find the point of intersection for the maximum speed found in Step (1) and the load mass. Select the bore size on the line above the point of intersection.

# Load Condition Operating Pressure Load in the direction at the right angle to rod

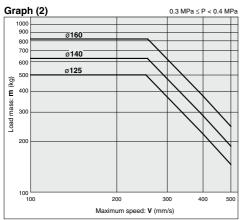
(\* Being held by a guide)

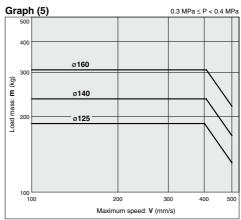


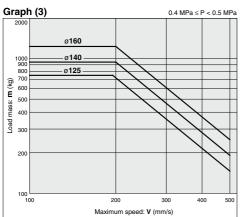
Load in the direction of rod extension Load in the direction of rod retraction

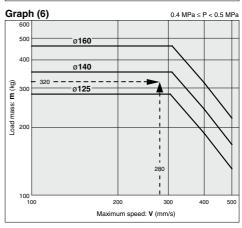


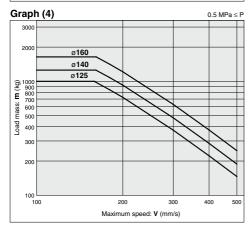
# **Selection Graph**

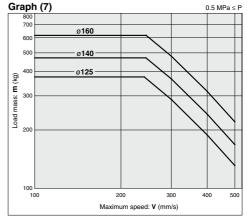






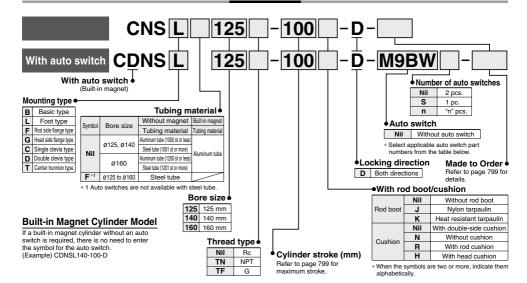






# Cylinder with Lock **Double Acting, Single Rod** CNS Series

# How to Order



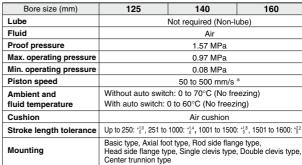
# Annlicable Auto Switches/Refer to

ø125, ø140, ø160

	DIICADIE AUTO SWIT		트		1.0	oad volta	ne er	Auto swit	ch model	Lead w	riro lo	nath	(m)											
Туре	Special function	Electrical entry	Indicator light	Wiring (Output)		C	AC	Tie-rod mounting	Band mounting	0.5 (Nil)	1 (M)	3	5	Pre-wired connector		ble load								
				3-wire (NPN)	24 V	5 V, 12 V		M9N	_	•	•	•	0	0	IC circuit									
		Grommet		3-wire (PNP)	24 V	5 V, 12 V		M9P	_	•	•	•	0	0	io circuit									
Æ	<del></del>			2-wire		12 V		M9B	_	•	•	•	0	_	_									
switch		Terminal		3-wire (NPN)		5 V, 12 V		_	G39	_	_	_	_	_	IC circuit									
S		conduit		2-wire		12 V		-	K39		-	-	-	_	_									
anto	Diagnostic indication			3-wire (NPN)		5 V, 12 V		M9NW	_	•	•	•	0	0	IC circuit	Relay,								
ā	(2-color indicator)			Yes	3-wire (PNP)				M9PW	_	• •	•	•	0	0	10 circuit	PLC							
tate	(= 55:5:)			2-wire	24 V	12 V	-	M9BW	_	•	•	•	0	0	_	1								
Solid state	Water resistant (2-color indicator) Grommet	Grommet	Grommet		3-wire (NPN)		5 V. 12 V		M9NA*1	_	0		•		0	IC circuit								
ĕ				Citiminet	Gionnine	aronnine	aronniet	aronniet	aronniet	arommet	aronninet	Gronniet		3-wire (PNP)		J V, 12 V		M9PA*1	_	0 (		•	0	0
Ñ				2-wire			12 V 5 V, 12 V	12 V		M9BA*1	_	0		•	0	0	_							
	With diagnostic output (2-color indicator)			4-wire (NPN)				5 V, 12 V		F59F	_	•	-	•		0	IC circuit							
	Magnetic field resistant (2-color indicator)			2-wire (Non-polar)		_		P3DWA	_	•	-	•	•	0	_									
_			Yes	3-wire (NPN equivalent)	_	5 V	_	A96	_	•	-	•	-	-	IC circuit	_								
switch		_				12 V	100 V	A93	_	•	•	•	•	_	_	Delen								
SW			No			5 V, 12 V	100 V or less	A90	_	•	I-	•	<del>-</del>	_	IC circuit	Relay, PLC								
육							100 V, 200 V	A54	_	•	-	•	•	_		1.20								
ä		Terminal	1	2-wire	24 V	12 V	_	_	A33	_	I-	-	_	_	1	PLC								
Reed auto		conduit	Yes			12 V	100 V. 200 V	_	A34		1-	-	_	_	1 —	Relay,								
"		DIN terminal					100 V, 200 V	_	A44	_	-	-	-			PLC								
	Diagnostic indication (2-color indicator)	Grommet				_	_	A59W	_	•	I-	•	-	_	]									

- \*1 Water resistant type auto switches can be mounted on the above models, but in such case SMC cannot guarantee water resistance.
- Consult with SMC regarding water resistant types with the above model numbers.
- \* Lead wire length symbols: 0.5 m ..... Nil (Example) M9NW (Example) M9NWL (Example) M9NWZ 1 m ···· M (Example) M9NWM 5 m .... Z
- \* Solid state auto switches marked with "O" are produced upon receipt of order.

# Cylinder Specifications



<sup>\*</sup> Load limits exist depending upon piston speed when locked, mounting direction and operating pressure.

# Lock Specifications

Bore size (mm)	125	140	160			
Locking action	Spring locking (Exhaust lock)					
Unlocking pressure	0.25 MPa or more					
Lock starting pressure	0.20 MPa or less					
Operating pressure range		0.25 to 0.7 MPa				
Locking direction	Both directions			Both directions		
Holding force (max. static load) kN *	8.4	10.5	13.8			

<sup>\*</sup> The holding force (max. static load) shows the maximum capability and does not show the normal holding capability. So, select an appropriate cylinder while referring to page 796.

# Symbol

Air cushion



# Made to Order Specifications Click here for details

Symbol	Specifications
-XA□	Change of rod end shape
-XC14	Change of trunnion bracket mounting position

### Refer to pages 811 to 813 for cylinders with auto switches.

- · Minimum auto switch mounting stroke
- · Proper auto switch mounting position (detection at stroke end) and mounting height
- · Operating range
- · Switch mounting bracket: Part no.

# Cylinder Stroke

			(mm		
Tube material Aluminum alloy		Carbon steel pipe			
Bore size (mm)	Bore size (mm)  Basic type, Head side flange type, Single clevis type, Double clevis type, Center trunnion type		Foot type, Rod side flange type		
125, 140	<b>125, 140</b> Up to 1000		Up to 1600		
160	<b>160</b> Up to 1200		Up to 1600		

# Cylinder Stroke/Auto Switch Mounting on Cylinder Unit (Built-in Magnet)

Refer to the minimum auto switch mounting stroke (page 812) for those with an auto switch.

		(11111)
Bore size (mm)	Basic type, Head side flange type, Single clevis type, Double clevis type, Center trunnion type	Foot type, Rod side flange type
125, 140	Up to 1000	Up to 1400
160	Up to 1200	Up to 1400

# Stopping Accuracy

			(mm)			
Lock type	Piston speed (mm/s)					
	100	300	500			
Spring locking	±0.5	±1.0	±2.0			

Condition: Lateral, Supply pressure P = 0.5 MPa
Load mass ······ Upper limit of allowed value
Solenoid valve for locking ···· Mounted directly to unlocking port

Maximum value of stopping position dispersion from 100 measurements



# Mounting Bracket Part No.

Bore size (mm)	125	140	160
Foot type (1)	CS1-L12	CS1-L14	CS1-L16
Rod side flange type (2)	CS1-FL12	CS1-FL14	CS1-FL16
Head side flange type	CS1-F12	CS1-F14	CS1-F16
Single clevis type	CS1-C12	CS1-C14	CS1-C16
Double clevis type (3)	CS1-D12	CS1-D14	CS1-D16

Note 1) When ordering foot bracket, order 2 pieces per cylinder.

Note 2) ø125 to ø160 rod side flange type use CS1 series long stroke flanges.

Note 3) Clevis pin and cotter pin (2 pcs.) are shipped together with double clevis type

# **Rod Boot Material**

Symbol	Rod boot material	Max. ambient temperature 70°C	
J	Nylon tarpaulin		
К	Heat resistant tarpaulin	110°C *	

<sup>\*</sup> Maximum ambient temperature for the rod boot itself.

# Accessory

Me	ounting bracket	Basic type	Foot type	Rod side type Flange side type	Head side flange type	Single clevis type	Double clevis type	Center trunnion type
Standard equipment	Clevis pin	_	_	_	_	-	•	-
	Rod end nut	•	•	•	•	•	•	•
Individual parts	Single knuckle joint	•	•	•	•	•	•	•
	Double knuckle joint (With pin)	•	•	•	•	•	•	•
Option	With rod boot	•	•	•	•	•	•	•

<sup>\*</sup> Refer to page 809 for the accessory bracket dimensions. (For rod boots, refer to page 802.)

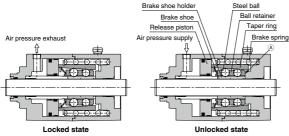
# Weight / ( ): Denotes the values for steel tube.

				(Kg
	Bore size (mm)	125	140	160
Lock unit	weight	14.40	20.20	30.60
	Basic type	28.79 (30.26)	37.67 (39.48)	55.31 (57.52)
	Foot type	30.42 (31.89)	40.19 (42.00)	58.11 (60.32)
Basic	Flange type	31.47 (32.94)	42.67 (44.48)	61.70 (63.91)
weight	Single clevis type	31.86 (33.33)	41.96 (43.77)	60.80 (63.01)
	Double clevis type (Including clevis pin and cotter pin)	32.32 (33.79)	42.71 (44.52)	61.65 (63.86)
	Trunnion type	32.92 (34.39)	43.40 (45.21)	62.71 (64.92)
Additional weight per each 100 mm of stroke		1.77 (2.66)	1.96 (3.01)	2.39 (3.58)
	Single knuckle joint	0.91	1.16	1.56
Accessory bracket	Double knuckle joint (With pin)	1.37	1.81	2.48
DIGOREL	Rod end nut	0.16	0.16	0.23

Calculation: (Example) CNSL140-100-D Basic weight................40.19 (Foot type, Ø140) Additional weight .....1.96/100 stroke Cylinder stroke ....... 100 stroke 40.19 + 1.96 x 100/100 = 42.15 kg

Brake shoe holder

# **Construction Principle**



### Spring locking (Exhaust lock)

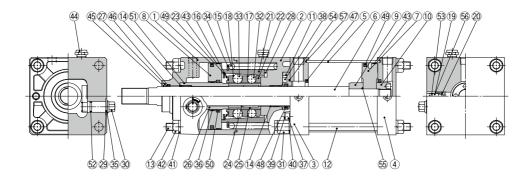
The spring force which acts upon the taper ring is magnified by a wedge effect, and is conveyed to all of the numerous steel balls which are arranged in two circles. These act on the brake shoe holder and brake, which locks the piston rod by tightening against it with a large force.

Unlocking is accomplished when air pressure is supplied to the unlocking port. The release piston and taper ring oppose the spring force, moving to the right side, and the ball retainer strikes the cover section A. The braking force is released as the steel balls are removed from the taper ring by the ball retainer.



<sup>\*\*</sup>Refer to page 810 when the rod end nut, and the single and double knuckle joints are used together.

# Construction



# **Component Parts**

No.	Description	Material	Note
1	Cover A	Aluminum alloy	Hard anodized and painted
2	Cover B	Aluminum alloy	Hard anodized and painted
3	Rod cover	Rolled steel plate	Black painted
4	Head cover	Rolled steel plate	Black painted
5	Cylinder tube	Aluminum alloy	Hard anodized
6	Piston rod	Carbon steel	Hard chrome plated
_ 7	Piston	Aluminum alloy casted	Chromated
8	Release piston	Aluminum alloy	Chromated
9	Cushion ring A	Rolled steel	Zinc chromated
_10	Cushion ring B	Rolled steel	Zinc chromated
11	Retaining plate B	Aluminum alloy	
12	Tie-rod A	Carbon steel	Chromated
13	Unit holding tie-rod	Carbon steel	Chromated
14	Bushing	Bearing alloy	
15	Brake spring	Steel wire	Black painted
16	Pre-load spring	Steel wire	Zinc chromated
_17	Clip A	Stainless steel wire	
18	Clip B	Stainless steel wire	
19	Cushion valve	Rolled steel	Electroless nickel plated
20	Valve guide	Brass	
21	Taper ring	Carbon steel	Heat treated
22	Ball retainer	Aluminum alloy	
23	Tooth ring	Stainless steel	
24	Brake shoe	Babbitt	
25	Brake shoe holder	Special steel	Heat treated
26	Piston guide	Carbon steel	Zinc chromated
27	Coil scraper mounting plate	Aluminum alloy	Anodized
28	Bumper	Polyurethane rubber	
29	Washer	Carbon steel	Zinc chromated

# O----- B---

Com	ponent Parts		
No.	Description	Material	Note
30	Unlocking cam	Carbon steel	Zinc chromated
31	Wing nut	Carbon steel	
32	Steel ball A	Carbon steel	
33	Steel ball B	Carbon steel	
34	Type C retaining ring for shaft (for taper ring)	Carbon steel	
35	Type C retaining ring for axis (for unlocking cam)	Carbon steel	
36	Bushing (for release piston)	Bearing alloy	
37	Hexagon socket head cap screw	Chromium molybdenum steel	
38	Hexagon socket head cap screw	Chromium molybdenum steel	
39	Conical spring washer	Spring steel	
40	Conical spring washer	Spring steel	
41	Spring washer	Steel wire	
42	Hexagon nut	Rolled steel	
43	Wear ring	Resin	
44	BC element		
45	Coil scraper	Phosphor bronze	
46	Wiper ring	NBR	
47	Cushion seal	NBR	
48	Rod seal	NBR	
49	Piston seal	NBR	
50	O-ring (for release piston)	NBR	
51	O-ring (for piston guide)	NBR	
52	O-ring (for unlocking cam)	NBR	
53	Valve seal	NBR	
54	Retaining plate gasket	NBR	
55	Piston gasket	NBR	
56	Guide gasket	NBR	
57	Tube gasket	NBR	, and the second

# Replacement Parts/Seal Kit

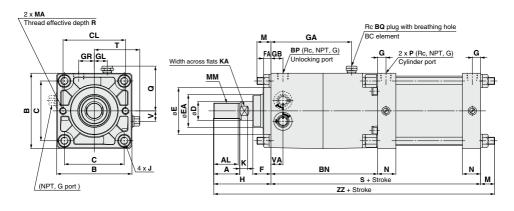
Bore size (mm)	Kit no.	Contents
125	CS1N125A-PS	
140	CS1N140A-PS	Set of above nos. 46, 48, 49, 53, 54, 57
160	CS1N160A-PS	9, 9, 9, 9, 9, 9

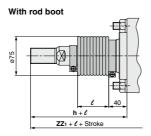
<sup>\*</sup> Since the lock section for the CNS series is normally replaced as a unit, kits are for the cylinder section only. These can be ordered using the order number for each bore size. \* Seal kit includes 像, 便, ⊕, ⑤, ⑤, ⑤, ① Creft he seal kit, based on each bore size. \* Seal kit includes a grease pack (40 g). Order with the following part number when only the grease pack is needed. Grease pack part no.: GR-S-010 (10 g), GR-S-020 (20 g)



# **Dimensions**

# Basic type (B): CNSB

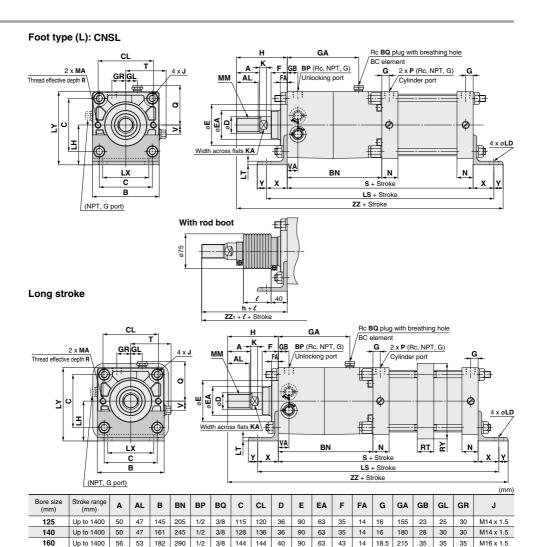




							_	_	_	_		_					_	_	_	(11111)
Bore size (mm)	Stroke range (mm)	A	AL	В	BN	ВР	BQ	С	CL	D	E	EA	F	FA	G	GA	GВ	GL	GR	J
125	Up to 1000	50	47	145	205	1/2	3/8	115	120	36	90	63	35	14	16	155	23	25	30	M14 x 1.5
140	Up to 1000	50	47	161	245	1/2	3/8	128	136	36	90	63	35	14	16	180	28	30	30	M14 x 1.5
160	Up to 1200	56	53	182	290	1/2	3/8	144	144	40	90	63	43	14	18.5	215	35	35	35	M16 x 1.5

															(mm)
Bore size (mm)	К	KA	М	MA	ММ	N	Р	Q	R	s	Т	٧	VA	н	ZZ
125	15	31	27	M12 x 1.75	M30 x 1.5	35	1/2	85.5	25	303	87.5	20	23	110	440
140	15	31	27	M12 x 1.75	M30 x 1.5	35	1/2	93.5	25	343	95	20	28	110	480
160	17	36	30.5	M12 x 1.75	M36 x 1.5	39	3/4	104	25	396	109	25	35	120	546.5

With Rod	Boot			(mm)
Bore size (mm)	Stroke range (mm)	ZZ <sub>1</sub>	e	h
125	30 to 1000	463		133
140	30 to 1000	503	1/5 stroke	133
160	30 to 1200	567.5		141



																						(mm)
Bore size (mm)	к	KA	LD	LH	LS	LT	LX	LY	MA	ММ	N	Р	Q	R	s	т	٧	VA	х	Y	н	zz
125	15	31	19	85	393	8	100	157.5	M12 x 1.75	M30 x 1.5	35	1/2	85.5	25	303	87.5	20	23	45	20	110	478
140	15	31	19	100	433	9	112	180.5	M12 x 1.75	M30 x 1.5	35	1/2	93.5	25	343	95	20	28	45	30	110	528
160	17	36	19	106	496	9	118	197	M12 x 1.75	M36 x 1.5	39	3/4	104	25	396	109	25	35	50	25	120	591

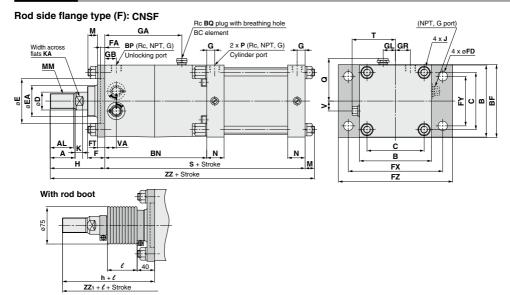
With Rod	Boot			(mm)
Bore size (mm)	Stroke range (mm)	ZZ <sub>1</sub>	e	h
125	30 to 1400	501		133
140	30 to 1400	551	1/5 stroke	133
160	30 to 1400	612		141

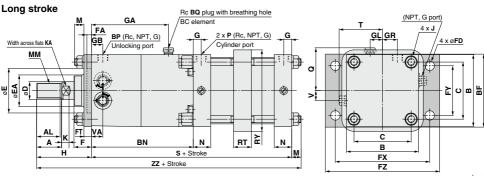
Long Stre	oke		(mm)
Bore size (mm)	Stroke range (mm)	RT	RY
125	1401 to 1600	36	164
140	1401 to 1600	36	184
160	1401 to 1600	45	204

<sup>\*</sup> Not available with auto switches.



# **Dimensions**





																					(111111)
Bore size (mm)	Stroke range (mm)	A	AL	В	BF	BN	ВР	BQ	С	D	E	EA	F	FA	FD	FT	FX	FY	FZ	G	GA
125	Up to 1400	50	47	145	145	205	1/2	3/8	115	36	90	63	35	14	19	14	190	100	230	16	155
140	Up to 1400	50	47	161	160	245	1/2	3/8	128	36	90	63	35	14	19	20	212	112	255	16	180
160	Up to 1400	56	53	182	180	290	1/2	3/8	144	40	90	63	43	14	19	20	236	118	275	18.5	215

(mm)

Bore size (mm)	GB	GL	GR	J	K	KA	М	ММ	N	Р	Q	s	Т	v	VA	н	zz
125	23	25	30	M14 x 1.5	15	31	19	M30 x 1.5	35	1/2	85.5	303	87.5	20	23	110	432
140	28	30	30	M14 x 1.5	15	31	19	M30 x 1.5	35	1/2	93.5	343	95	20	28	110	472
160	35	35	35	M16 x 1.5	17	36	22	M36 x 1.5	39	3/4	104	396	109	25	35	120	538

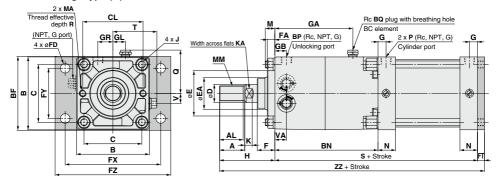
With Rod	Boot			(mm)
Bore size (mm)	Stroke range (mm)	ZZ <sub>1</sub>	e	h
125	30 to 1400	455		133
140	30 to 1400	495	1/5 stroke	133
160	30 to 1400	559		141

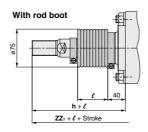
Long Stre	oke		(mm)
Bore size (mm)	Stroke range (mm)	RT	RY
125	1401 to 1600	36	164
140	1401 to 1600	36	184
160	1401 to 1600	45	204

<sup>\*</sup> Not available with auto switches.



# Head side flange type (G): CNSG





																						(mm)
Bore size (mm)	Stroke range (mm)	A	AL	В	BF	BN	ВР	BQ	С	CL	D	E	EA	F	FA	FD	FT	FX	FY	FZ	G	GA
125	Up to 1000	50	47	145	145	205	1/2	3/8	115	120	36	90	63	35	14	19	14	190	100	230	16	155
140	Up to 1000	50	47	161	160	245	1/2	3/8	128	136	36	90	63	35	14	19	20	212	112	255	16	180
160	Up to 1200	56	53	182	180	290	1/2	3/8	144	144	40	90	63	43	14	19	20	236	118	275	18.5	215

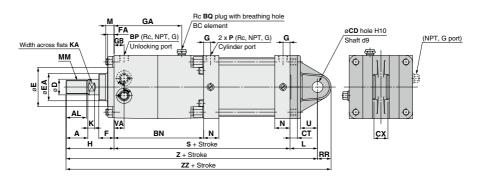
																			(mm)
Bore size (mm)	GB	GL	GR	J	к	KA	М	MA	ММ	N	Р	Q	R	s	Т	٧	VA	н	zz
125	23	25	30	M14 x 1.5	15	31	19	M12 x 1.75	M30 x 1.5	35	1/2	85.5	25	303	87.5	20	23	110	427
140	28	30	30	M14 x 1.5	15	31	19	M12 x 1.75	M30 x 1.5	35	1/2	93.5	25	343	95	20	28	110	473
160	35	35	35	M16 x 1.5	17	36	22	M12 x 1.75	M36 x 1.5	39	3/4	104	25	396	109	25	35	120	536

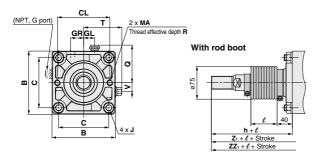
With Rod	Boot			(mm)
Bore size (mm)	Stroke range (mm)	ZZ <sub>1</sub>	e	h
125	30 to 1000	450		133
140	30 to 1000	496	1/5 stroke	133
160	30 to 1200	557		141

**SMC** 

# **Dimensions**

# Single clevis type (C): CNSC



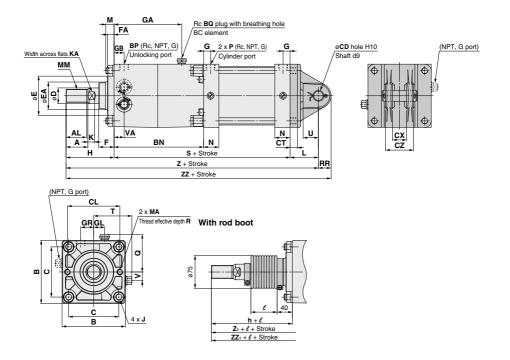


																					(mm)
Bore size (mm)	Stroke range (mm)	A	AL	В	BN	ВР	BQ	С	CD <sub>H10</sub>	CL	СТ	сх	D	E	EA	F	FA	G	GA	GB	GL
125	Up to 1000	50	47	145	205	1/2	3/8	115	25 +0.084	120	17	32 -0.1	36	90	63	35	14	16	155	23	25
140	Up to 1000	50	47	161	245	1/2	3/8	128	28 +0.084	136	17	36 -0.1	36	90	63	35	14	16	180	28	30
160	Up to 1200	56	53	182	290	1/2	3/8	144	32 +0.100	144	20	40 -0.1	40	90	63	43	14	18.5	215	35	35

Bore size (mm)	GR	J	к	KA	L	М	MA	ММ	N	Р	Q	R	RR	s	т	U	v	VA	Н	z	zz
125	30	M14 x 1.5	15	31	65	19	M12 x 1.75	M30 x 1.5	35	1/2	85.5	25	29	303	87.5	35	20	23	110	478	507
140	30	M14 x 1.5	15	31	75	19	M12 x 1.75	M30 x 1.5	35	1/2	93.5	25	32	343	95	40	20	28	110	528	560
160	35	M16 x 1.5	17	36	80	22	M12 x 1.75	M36 x 1.5	39	3/4	104	25	36	396	109	45	25	35	120	596	632

With Rod	Boot				(mm)
Bore size (mm)	Stroke range (mm)	Z <sub>1</sub>	ZZ <sub>1</sub>	e	h
125	30 to 1000	501	530		133
140	30 to 1000	551	583	1/s stroke	133
160	30 to 1200	617	653		141

# Double clevis type (D): CNSD



Bore size (mm)	Stroke range (mm)	Α	AL	В	BN	ВР	BQ	С	<b>CD</b> <sub>H10</sub>	CL	СТ	СХ	CZ	D	E	EA	F	FA
125	Up to 1000	50	47	145	205	1/2	3/8	115	25 +0.084	120	17	32 +0.3	64 -0.2	36	90	63	35	14
140	Up to 1000	50	47	161	245	1/2	3/8	128	28 +0.084	136	17	36 +0.3	72 -0.2	36	90	63	35	14
160	Up to 1200	56	53	182	290	1/2	3/8	144	32 +0.100	144	20	40 +0.3	80 _0.2	40	90	63	43	14

																			(mm)
Bore size (mm)	G	GA	GB	GL	GR	J	к	KA	L	М	MA	ММ	N	Р	Ø	R	RR	s	т
125	16	155	23	25	30	M14 x 1.5	15	31	65	19	M12 x 1.75	M30 x 1.5	35	1/2	85.5	25	29	303	87.5
140	16	180	28	30	30	M14 x 1.5	15	31	75	19	M12 x 1.75	M30 x 1.5	35	1/2	93.5	25	32	343	95
160	18.5	215	35	35	35	M16 x 1.5	17	36	80	22	M12 x 1.75	M36 x 1.5	39	3/4	104	25	36	396	109

					(mm)
U	٧	VA	н	z	zz
35	20	23	110	478	507
40	20	28	110	528	560
45	25	35	120	596	632
	35 40	35 20 40 20	35 20 23 40 20 28	35 20 23 110 40 20 28 110	35 20 23 110 478 40 20 28 110 528

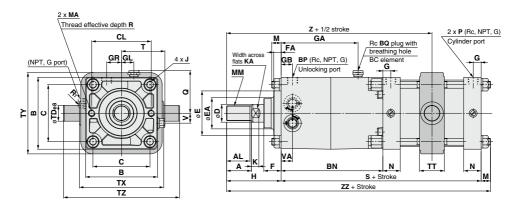
With Rod	Boot				(mm)
Bore size (mm)	Stroke range (mm)	Z <sub>1</sub>	ZZ <sub>1</sub>	e	h
125	30 to 1000	501	530		133
140	30 to 1000	551	583	1/s stroke	133
160	30 to 1200	617	653		141

<sup>\*</sup> Clevis pin and cotter pin are shipped together.

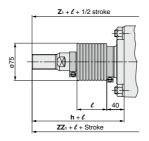


# **Dimensions**

# Center trunnion type (T): CNST



# With rod boot



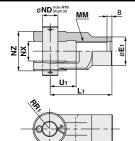
																						(mm)
Bore size (mm)	Stroke range (mm)	A	AL	В	BN	ВР	BQ	С	CL	D	E	EA	F	FA	G	GA	GB	GL	GR	J	к	KA
125	25 to 1000	50	47	145	205	1/2	3/8	115	120	36	90	63	35	14	16	155	23	25	30	M14 x 1.5	15	31
140	30 to 1000	50	47	161	245	1/2	3/8	128	136	36	90	63	35	14	16	180	28	30	30	M14 x 1.5	15	31
160	35 to 1200	56	53	182	290	1/2	3/8	144	144	40	90	63	43	14	18.5	215	35	35	35	M16 x 1.5	17	36

																				(mm)
Bore size (mm)	М	MA	ММ	N	Р	Q	R	Rı	s	Т	TD <sub>e8</sub>	TT	тх	TY	TZ	v	VA	н	z	zz
125	19	M12 x 1.75	M30 x 1.5	35	1/2	85.5	25	1	303	87.5	32 -0.050	50	170	164	234	20	23	110	364	432
140	19	M12 x 1.75	M30 x 1.5	35	1/2	93.5	25	1.5	343	95	36 -0.050	55	190	184	262	20	28	110	404	472
160	22	M12 x 1.75	M36 x 1.5	39	3/4	104	25	1.5	396	109	40 -0.050	60	212	204	292	25	35	120	463	538

With Rod Boot (mm													
Bore size (mm)	Stroke range (mm)	Z <sub>1</sub>	ZZ <sub>1</sub>	e	h								
125	30 to 1000	387	455		133								
140	30 to 1000	427	495	1/5 stroke	133								
160	35 to 1200	484	559		141								

# **Accessory Bracket Dimensions 1**

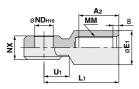
# Y Type Double Knuckle Joint

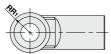


widteria	. Odot iron								(mm
Part no.	Applicable bore size (mm)	E1	L <sub>1</sub>	ММ	ND <sub>H10</sub>	NX	NZ	RR1	U1
Y-12	125	46	100	M30 x 1.5	25 +0.084	32 +0.3	64 -0.1	27	42
Y-14	140	48	105	M30 x 1.5	28 +0.084	36 +0.3	72 -0.1	30	47
Y-16	160	55	110	M36 x 1.5	32 +0.1	40 +0.3	80 -0.1	34	46

<sup>\*</sup> Knuckle pins and cotter pins are included

# **I Type Single Knuckle Joint**

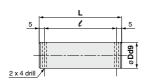




# Material: Cast iron

Material: Cas	st iron								(mm)
Part no.	Applicable bore size (mm)	<b>A</b> 2	E1	L1	ММ	ND <sub>H10</sub>	NX	RR1	U1
I-12	125	54	46	100	M30 x 1.5	25 +0.084	32 -0.1	27	33
I-14	140	54	48	105	M30 x 1.5	28 +0.084	36 -0.1	30	39
I-16	160	60	55	110	M36 x 1.5	32 *0.1	40 -0.1	34	39

# Clevis Pin/Knuckle Pin

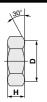


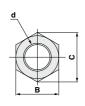
### Material: Carbon steel

waterial. Oak	(11111)				
Part no.	Applicable bore size (mm)	Dd9	L	e	Applicable cotter pin
IY-12	125	25 -0.065 -0.117	79.5	69.5	ø4 x 40 L
IY-14	140	28 -0.065 -0.117	86.5	76.5	ø4 x 40 L
IY-16	160	32 -0.080	94.5	84.5	ø4 x 40 L

<sup>\*</sup> Cotter pins (2 pcs.) are included.

# **Rod End Nut**

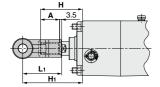




Material	Material: Rolled steel (mm)											
Part no.	Applicable bore size (mm)	d	н	В	С	D						
NT-12	125,140	M30 x 1.5	18	46	53.1	44						
NT-16	160	M36 x 1.5	21	55	63.5	53						

# **Accessory Bracket Dimensions 2**

# Single/Double Knuckle Joint Mounting



						(mm)	
Bore Symbol	н	Α	L1	H1	Applicable knuckle joint part no.		
size (mm)	-	_ ^		п п	I type single knuckle	Y type double knuckle	
125	110	50	100	156.5	I-12	Y-12	
140	110	50	105	161.5	I-14	Y-14	
160	120	56	110	170.5	I-16	Y-16	

A, H Dimensions When Mounting a Single/Double Knuckle Joint together with a Rod End Nut

Bore size (mm)	Α	Н
125	65	125
140	65	125
160	76	140

<sup>\*</sup> Single knuckle joint and double knuckle joint should be used separately.

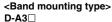
(Fasten by screwing completely into the rod end threads.)

• Extent the dimensions of A and H, when using a single/double knuckle joint together with a rod end nut.

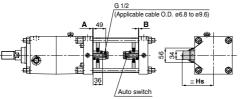
For extension of A and H dimensions, refer to the table above and specify "Simple Specials -XAO" (page 1478).

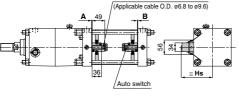
# **CNS** Series **Auto Switch Mounting 1**

Auto Switch Proper Mounting Position (Detection at Stroke End) and Its Mounting Height



D-G39/K39



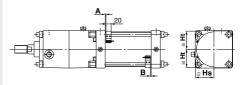




D-M9□/M9□V D-Z7□/Z80

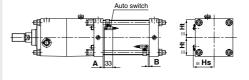
D-M9□W/M9□WV D-Y59 - /Y69 - /Y7P/Y7PV D-M9 A/M9 AV D-Y7 W/Y7 WV

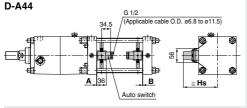
D-Y7BA D-A9□/A9□V





D-P3DWA

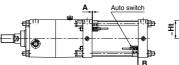




# D-F5 J59/D-F5NTL D-F5BA/F59F

# D-F5□W/J59W







### Auto Switch Proper Mounting Position

AULU UN		··opc	I IVIO	untin	g i oa	111011										(111111)
Auto switch model		□V □W □WV □A	D-A D-A	9□ 9□V	D-Z7 D-Y5 D-Y7P D-Y7 D-Y7 D-Y7	JY6□ JY7PV W WV	D-A	39	D-A	59W	D-F5 D-J5 D-F5 D-F5 D-J5	9W BA i□ i9	D-F	5NT	D-P3	DWA
(mm)	Α	В	Α	В	Α	В	Α	В	Α	В	Α	В	Α	В	Α	В
125	8	8	4	4	1.5	1.5	0	0	2	2	4.5	4.5	9.5	9.5	3.5	3.5
140	8	8	4	4	1.5	1.5	0	0	2	2	4.5	4.5	9.5	9.5	3.5	3.5
160	8	8	4	4	1.5	1.5	0	0	2	2	4.5	4.5	9.5	9.5	3.5	3.5

<sup>\*</sup> The above shown are the proper auto switch mounting positions for detection at stroke end. Adjust the auto switch after confirming the operating conditions in the actual setting.

Auto Sw	itch l	Moun	ting I	leigh	t									(mm)
Auto switch model	D-M	9□W 9□A	D-M9 D-M9 D-M9	□wv	D-Z7 D-Y5 D-Y7F D-Y7F D-Y7 D-Y7	J/Y6□ PV □W	D-A3□ D-G39 D-K39	D-A44	D-A5□ D-A6□ D-A59W		D-F5 D-J5 D-F5 D-F5 D-F5 D-F5	i9 i⊟W i9W iBA i9F	D-P3DWA	
(mm)	Hs	Ht	Hs	Ht	Hs	Ht	Hs	Hs	Hs	Ht	Hs	Ht	Hs	Ht
125	69	69.5	71.5	69.5	69	69.5	116	126	75.5	69.5	74.5	70	76	69.5
140	76	76	77.5	76	76	76	124	134	81	76.5	80	76.5	82	76
160	85	85	86	85	85	85	134.5	144.5	89	87.5	88	87.5	91	85

# CNS Series Auto Switch Mounting 2

# **Minimum Stroke for Auto Switch Mounting**

					na Nauesteen	of auto switch (mm
A		No. of out-	Manadian bandada		n: Number of	of auto switch (mm)
Auto switch model	Sv	No. of auto witches mounted	Mounting brackets other than center trunnion	ø125	ø140	ø160
	-	ifferent surfaces, Same surface)	15	105	110	115
D-M9□	<u> </u>	1				
D-M9□W		n	15 + 40 (n-2)	105 + 40 (n-4)	110 + 40 (n - 4)	115 + 40 (n - 4)
			(n = 2, 4, 6, 8 ···) Note 1)	(n = 4, 8, 12, 16 ···) Note 2)	(n = 4, 8, 12, 16 ···) Note 2)	(n = 4, 8, 12, 16 ···) Note 2)
D MODV	2 (Different surfaces, Same surface) 1		10	80	85	90
D-M9□V D-M9□WV	Н		10 + 30 (n-2)	80 + 30 (n - 4)	85 + 30 (n - 4)	90 + 30 (n - 4)
		n			(n = 4, 8, 12, 16 ···) Note 2)	
	2 (Di	ifferent surfaces, Same surface)	20	115		20
D-M9□A	L	1				
D-INI3		n	20 + 40 (n-2)	115 + 40 (n - 4)		0 (n - 4)
			(n = 2, 4, 6, 8 ···) Note 1)	(n = 4, 8, 12, 16 ···) Note 2)	(n = 4, 8, 12	, 16 ···) Note 2)
	2 (Di	ifferent surfaces, Same surface)	15	90	9	5
D-M9□AV	H		15 + 30 (n-2)	90 + 30 (n - 4)	95 + 30	(n - 4)
		n		(n = 4, 8, 12, 16 ···) Note 2)		, 16 ···) Note 2)
	2 (Di	ifferent surfaces, Same surface)	15	100	105	
D-A9□	L	1				110
D-A9		n	15 + 40 (n-2)	100 + 40 (n - 4)	105 + 40 (n - 4)	110 + 40 (n - 4)
			(n = 2, 4, 6, 8 ···) Note 1)	(n = 4, 8, 12, 16 ···) Note 2)	(n = 4, 8, 12, 16 ···) Note 2)	(n = 4, 8, 12, 16 ···) Note 2)
	2 (Di	ifferent surfaces, Same surface)	10	75	80	85
D-A9□V	$\vdash$	•	10 + 30 (n-2)	75 + 30 (n - 4)	80 + 30 (n - 4)	85 + 30 (n - 4)
		n			(n = 4, 8, 12, 16 ···) Note 2)	(n = 4 8 12 16) Note 2)
D-A5/A6	2 (Di	ifferent surfaces, Same surface)				-
D-A59W D-F5 = /J59	Ľ	1	25	125		35
D-A5/A6 D-A59W D-F5□/J59 D-F5□W D-J59W	l n	(Same surface)	$25 + 55 \frac{(n-2)}{2}$	125 + 55 (n - 4)	135 + 5	
D-559W D-F5BA D-F59F			(n = 2, 4, 6, 8 ···) Note 1)	(n = 4, 8, 12, 16 ···) Note 2)	(n = 4, 8, 12	, 16 ···) Note 2)
	2 (Di	ifferent surfaces, Same surface)	35	145	15	55
D-F5NT	$\vdash$	· ·	35 + 55 (n-2)	145 + 55 (n - 4)	155 . 5	5 (n - 4)
	n	(Same surface)		(n = 4, 8, 12, 16 ···) Note 2)		, 16 ···) <sup>Note 2)</sup>
	2	Different surfaces	35	(11 = 1, 0, 12, 10 )	110	, /
_	Ľ	Same surface	100			
D-A3□ D-G39		Different surfaces	35 + 30 (n - 2) (n = 2, 3, 4, 5 ···)		110 + 30 (n - 2) (n = 2, 4, 6, 8 ···) Note 1	)
D-K39	n		100 + 100 (n - 2)		110 + 100 (n – 2)	-
	Ш	Same surface	(n = 2, 3, 4, 5 ···)		(n = 2, 4, 6, 8 ···) Note 1	)
	Н	1	15 35		110	
	2	Different surfaces Same surface	55		110	
	П	Different surfaces	35 + 30 (n - 2)		110 + 30 (n - 2)	
D-A44	n	Dillerent surfaces	(n = 2, 3, 4, 5 ···)		(n = 2, 4, 6, 8 ···) Note 1	)
		Same surface	55 + 55 (n - 2) (n = 2, 3, 4, 5 ···)		110 + 50 (n - 2) (n = 2, 4, 6, 8 ···) Note 1	)
	г	1	15		110	
D-Z7□	2 (Di	ifferent surfaces, Same surface)	15	105	110	115
D-Z80 D-Y59□	⊢	1				
D-Y7P		n	15 + 40 (n-2)	105 + 40 (n - 4)	110 + 40 (n - 4)	115 + 40 (n - 4)
D-Y7□W	2 /Di	ifferent surfaces, Same surface)			(n = 4, 8, 12, 16 ···) Note 2)	
D-Y69□	_ (5)	1	10	90	95	100
D-Y7PV D-Y7□WV		n	10 + 30 (n-2)	90 + 30 (n - 4) 2	95 + 30 (n - 4)	100 + 30 (n - 4)
2-17-144 A			(n = 2, 4, 6, 8 ···) Note 1)	(n = 4, 8, 12, 16 ···) Note 2)	(n = 4, 8, 12, 16 ···) Note 2)	(n = 4, 8, 12, 16 ···) Note 2)
	2 (Di	ifferent surfaces, Same surface)	20	115	120	125
D-Y7BA	$\vdash$	1	00 45 (n - 2)	445 45 (n – 4)	100 15 (n - 4)	125 + 45 (n - 4)
		n	20 + 45 (n - 2) (n - 2 4 6 8 Note 1)	115 + 45 (n - 4)	120 + 45 (n - 4)	
	2 (Di	ifferent surfaces, Same surface)			(n = 4, 8, 12, 16 ···) Note 2)	
	L	1	20	110	115	120
D-P3DWA		n	$20 + 50 \frac{(n-2)}{2}$	110 + 50 (n - 4)	115 + 50 (n - 4)	120 + 50 (n - 4)
		"			(n = 4, 8, 12, 16 ···) Note 2)	
	_					

Note 1) When "n" is an odd number, an even number that is one larger than this odd number is used for the calculation.



Note 2) When "n" is an odd number, a multiple of 4 that is larger than this odd number is used for the calculation.

# **Operating Range**

			(mm)			
Auto switch model	Е	Bore size				
Auto Switch model	125	140	160			
D-M9□/M9□V D-M9□W/M9□WV D-M9□A/M9□AV	7	6.5	6.5			
D-A9□/A9□V	12	12.5	11.5			
D-Z7□/Z80	14	14.5	13			
D-A3□/A44 D-A5□/A6□	10	10	10			
D-A59W	17	17	17			
D-Y59□/Y69□ D-Y7P/Y7PV D-Y7□W/Y7□WV D-Y7BA	12	13	7			
D-F59F/F5□/J59 D-F5□W/J59W D-F5BA/F5NT	5	5	5.5			
D-G39/K39	11	11	10			
D-P3DWA	6	6.5	6.5			

<sup>\*</sup> Since the operating range is provided as a guideline including hysteresis, it cannot be guaranteed (assuming approximately ±30% dispersion). It may vary substantially depending on an ambient environment.

# Auto Switch Mounting Bracket: Part No.

Auto switch model		Bore size (mm)	
Auto switch model	ø <b>125</b>	ø <b>140</b>	ø160
D-M9□/M9□V D-M9□W/M9□WV D-M9□A/M9□AV D-A9□/A9□V	BS5-125	BS5-125	BS5-160
D-A5/A6/A59W D-F5□/J59/F5NT D-F5□W/J59W D-F5BA/F59F	BT-12	BT-12	BT-16
D-A3□/A44 D-G39/K39	BS1-125	BS1-140	BS1-160
D-Z7□/Z80 D-Y59□/Y69□ D-Y7P/Y7PV D-Y7□W/Y7□WV D-Y7BA	BS4-125	BS4-125	BS4-160
D-P3DWA	BS7-125S	BS7-125S	BS7-160S

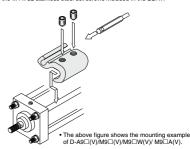
### [Mounting screw set made of stainless steel]

The following set of mounting screws made of stainless steel (including nuts) is available. Use it in accordance with the operating environment. (Please order the auto switch mounting bracket separately, since it is not included.)

BBA1: For D-A5/A6/F5/J5 types
D-F5BA auto switch is set on the cylinder with the stainless steel screws above when shipped. When an auto switch is shipped independently, BBA1 is attached.

Note 1) Refer to page 1447 for the details of BBA1.

Note 2) When using D-M9□A(V)Y7BA, do not use the steel set screws which is included with the auto switch mounting brackets above (BS5-□□□, BS4-□□□). Order a stainless steel screw set (BBA1) separately, and select and use the M4 x 8L stainless steel set screws included in the BBA1.



Other than the applicable auto switches listed in "How to Order", the following auto switches can be mounted. For detailed specifications, refer to pages 1341 to 1435.

Auto switch type	Model	Electrical entry (Fetching direction)	Features	
	D-A90V		Without indicator light	
	D-A93V, A96V	Grommet (Perpendicular)		
Reed	D-Z73, Z76		<u> </u>	
neea	D-A53, A56	O		
	D-A64, A67	Grommet (In-line)	Without indicator light	
	D-Z80			
	D-M9NV, M9PV, M9BV		_	
	D-Y69A, Y69B, Y7PV			
	D-M9NWV, M9PWV, M9BWV	Grommet (Perpendicular)	2-color indicator	
	D-Y7NWV, Y7PWV, Y7BWV			
	D-M9NAV, M9PAV, M9BAV		Water resistant (2-color indicator)	
Solid state	D-F59, F5P, J59			
	D-Y59A, Y59B, Y7P		_	
	D-F59W, F5PW, J59W	O	2-color indicator	
	D-Y7NW, Y7PW, Y7BW	Grommet (In-line)		
	D-F5BA, Y7BA		Water resistant (2-color indicator)	
	D-F5NT		With timer	

<sup>\*</sup> With pre-wired connector is available for solid state auto switches. For details, refer to pages 1410 and 1411.

<sup>\*</sup> Normally closed (NC = b contact) solid state auto switches (D-M9□E(V)/Y7G/Y7H) are also available. For details, refer to pages 1360 and 1362.



Be sure to read this before handling the products.

Refer to page 9 for safety instructions and pages 10 to 19 for actuator and auto switch precautions.

# **Design of Equipment and Machinery**

# ⚠Warning

 Construct so that the human body will not come into direct contact with driven objects or the moving parts of the cylinders with lock.

Devise a safe structure by attaching protective covers that prevent direct contact with the human body, or in cases where there is a danger of contact, provide sensors or other devices to perform an emergency stop, etc., before contact occurs.

2. Use a balance circuit, taking cylinder lurching into consideration.

In cases such as an intermediate stop, where a look is operated at a desired position within the stroke and air pressure is applied from only one side of the cylinder, the piston will lurch at high speed when the lock is released. In such situations, there is a danger of causing human injury by having hands or feet, etc. caught, and also a danger for causing damage to the equipment. In order to prevent this lurching, a balance circuit such as the recommended pneumatic circuits (pages 815 and 816) should be used.

### Selection

# **△Warning**

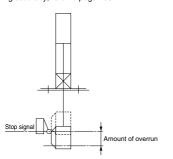
 When in the locked state, do not apply a load accompanied by an impact shock, strong vibration or turning force, etc.

Use caution, because an external action such as an impacting load, strong vibration or turning force, may damage the locking mechanism or reduce its life.

2. Consider stopping accuracy and the amount of over-run when an intermediate stop is performed.

Due to the nature of a mechanical lock, there is a momentary lag with respect to the stop signal, and a time delay occurs before stopping. The cylinder stroke resulting from this delay is the overrun amount. The difference between the maximum and minimum overrun amounts is the stopping accuracy.

- Place a limit switch before the desired stopping position, at a distance equal to the overrun amount.
- The limit switch must have a detection length (dog length) of the overrun amount +  $\alpha.$
- SMC auto switches have operating ranges from 8 to 14 mm (depending on the switch model).
- When the overrun amount exceeds this range, self-holding of the contact should be performed at the switch load side.
- \*For stopping accuracy, refer to page 799.



### Selection

# **⚠**Warning

In order to further improve stopping accuracy, the time from the stop signal to the operation of the lock should be shortened as much as possible.

To accomplish this, use a device such as a highly responsive electric control circuit or solenoid valve driven by direct current, and place the solenoid valve as close as possible to the cylinder.

Note that the stopping accuracy will be influenced by changes in piston speed.

When piston speed changes during the course of the cylinder stroke due to variations in the load or disturbances, etc., the dispersion of stopping positions will increase. Therefore, consideration should be given to establishing a standard speed for the piston just before it reaches the stopping position.

Moreover, the dispersion of stopping positions will increase during the cushioned portion of the stroke and during the accelerating portion of the stroke after the start of operation, due to the large changes in piston speed.

5. The holding force (max. static load) indicates the maximum capability to hold a static load without loads, vibration and impact. This does not indicate a load that can be held in ordinary conditions.

Select the most suitable bore sizes for the operating conditions in accordance with the selection procedures. The Model Selection (pages 796 and 797) is based on use at the intermediate stop (including emergency stops during the operation). However, when the cylinder is in a locked state, kinetic energy does not act upon it. Under these conditions, use the load mass at the maximum speed (V) of 100 mm/s shown in the graphs 5 to 7 on page 797 depending on the operating pressure and select models.

# Mounting

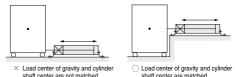
# **≜**Warning

 Be certain to connect the rod end to the load with the lock released.

If connected in the locked state, a load greater than the turning force or holding force, etc. may operate on the piston rod and cause damage to the lock mechanism. The CNS series is equipped with an emergency unlocking mechanism; however, when connecting the rod end to the load, this should be done with the lock released. This can be accomplished by simply connecting an air line to the unlocking port and supplying air pressure of 0.25 MPa or more.

2. Do not apply offset loads to the piston rod.

Particular care should be taken to match the load's center of gravity with the center of the cylinder shaft. When there is a large discrepancy, the piston rod may be subjected to uneven wear or damage due to the inertial moment during locking stops.



Note) Can be used if all of the generated moment is absorbed by an effective guide.





Be sure to read this before handling the products.

Refer to page 9 for safety instructions and pages 10 to 19 for actuator and auto switch precautions.

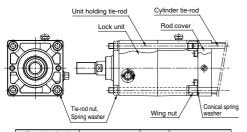
# Mounting

# **∕**∴Caution

 Caution on using the basic type or replacing the support bracket.

The lock unit and cylinder rod cover are assembled as shown in the figure below. For this reason, it cannot be installed as in the case of common air cylinders, by using the basic type and screwing the cylinder tie-rods directly to machinery.

Furthermore, when replacing mounting brackets, the unit holding tie-rods may get loosen. Tighten them once again in such a case.



l	Bore size (mm)	Tie-rod nut	Width across flats	Socket
	125 140	JIS B 1181 Class 2 M14 x 1.5	22	JIS B 4636 socket 22
	160	JIS B 1181 Class 2 M16 x 1.5	24	JIS B 4636 socket 24

# Adjustment

# **∧** Caution

1. Adjust the cylinder's air balance.

Balance the load by adjusting the air pressure in the rod and head sides of the cylinder with the load connected to the cylinder and the lock released. Lurching of the cylinder when unlocked can be prevented by carefully adjusting this air balance.

Adjust the mounting positions of the detectors on auto switches, etc.

When intermediate stops are to be performed, adjust the mounting positions of detectors on auto switches, etc., taking into consideration the overrun amount with respect to the desired stopping positions.

3. Do not open the cushion valve excessively.

If the cushion valve is rotated excessively in the opening direction (counterclockwise), it could be damaged. Be aware that the valve could slip out, or the threads becomes too short.

### **Pneumatic Circuit**

# 

 Be certain to use an pneumatic circuit which will apply balancing pressure to both sides of the piston when in a locked stop.

In order to prevent cylinder lurching after a lock stop, when restarting or when manually unlocking, a circuit should be used to which will apply balancing pressure to both sides of the piston, thereby canceling the force generated by the load in the direction of piston movement.

### Pneumatic Circuit

# **⚠**Warning

The effective area of the lock release solenoid valve should be at least 50% of the effective area of the cylinder driving solenoid valve, and it should be installed as close to the cylinder as possible so that is closer than the cylinder driving solenoid valve.

If the effective area of the lock release solenoid valve is small or if it is installed at a distance from the cylinder, the time required for exhausting air for releasing the lock will be longer, which may cause a delay in the locking operation.

The delay in the locking operation may result in problems such as increase of overrunning when performing intermediate stop or emergency stop during operation, or if maintaining position from the operation stop state such as drop prevention, workpieces may be dropped depending on the timing of the load action to the operation delay of the lock.

Avoid backflow of the exhaust pressure when there is a possibility of interference of exhaust air, for example for a common exhaust type valve manifold.

The lock may not operate properly when the exhaust air pressure backflows due to interference of the exhaust air when exhausting air for lock release. It is recommended to use an individual exhaust type manifold or individual valves.

 Allow at least 0.5 seconds from a locked stop (intermediate stop of the cylinder) until release of the lock.

When the locked stop time is too short, the piston rod (and load) may lurch at a speed greater than the controlls peed of the speed controller.

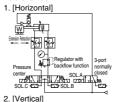
When restarting, control the switching signal for the unlocking solenoid valve so that it acts before or at the same time as the cylinder drive solenoid valve.

If the signal is delayed, the piston rod (and load) may lurch at a speed greater than the control speed of the speed controller.

6. Carefully check for dew condensation due to repeated air supply and exhaust of the locking solenoid valve.

The operating stroke of the lock part is very small. So, if the piping is long and the air supply and exhaust are repeated, the dew condensation caused by the adiabatic expansion accumulates in the lock part. This may corrode internal parts, causing air leak or lock release fault.

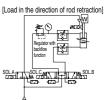
### 7. Basic circuit





[Load in the direction of rod extension]
[Load in the direction of rod extension]

Regulator with backflow function S was SULA WAS SOLA CONTROL OF SOLA CONTROL O



 The symbol for the cylinder with lock in the basic circuit uses SMC original symbol.



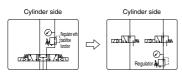
Be sure to read this before handling the products.

Refer to page 9 for safety instructions and pages 10 to 19 for actuator and auto switch precautions.

# **Pneumatic Circuit**

# **⚠Caution**

 3-position pressure center solenoid valve and regulator with backflow function can be replaced with two 3-port normally open valves and a regulator with relief function.



# [Example]

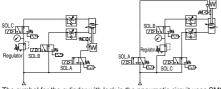
1. [Horizontal]



[Vertical]

[Load in the direction of rod extension]

[Load in the direction of rod retraction]



 The symbol for the cylinder with lock in the pneumatic circuit uses SMC original symbol.

# Manually Unlocking

# **.**Marning

- 1. Never operate the unlocking cam until safety has been confirmed. (Do not turn to the FREE side.)
  - When unlocking is performed with air pressure applied to only one side of the cylinder, the moving parts of the cylinder will lurch at high speed causing a serious hazard.
  - When unlocking is performed, be sure to confirm that personnel are not within the load movement range and that no other problems will occur if the load moves.
- Before operating the unlocking cam, exhaust any residual pressure which is in the system.
- Take measures to prevent the load from dropping when unlocking is performed.
  - Perform work with the load in its lowest position.
  - Take measures for drop prevention by strut, etc.
  - Confirm that balanced pressure is applied to both sides of the piston.

# 

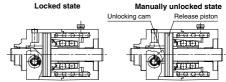
 The unlocking cam is an emergency unlocking mechanism only.

During an emergency when the air supply is stopped or cut off, this is used to alleviate a problem by forcibly pushing back the release piston and brake spring to release the lock.

- When installing the cylinder into equipment or performing adjustments, etc., be sure to apply an pressure of 0.25 MPa or more to the unlocking port, and do not perform work using the unlocking cam.
- When releasing the lock with the unlocking cam, it must be noted that the sliding resistance of the cylinder will be high, unlike normal unlocking with air pressure.

Bore size (mm)	Cylinder sliding resistance (N)	Cam unlocking torque (standard) (N·m)	Width across flats (mm)	Socket
125	961	68.6	16	JIS B 4636 socket 16
140	1216	78.4	18	JIS B 4636 socket 18
160	1579	156.8	21	JIS B 4636 socket 21

- 4. Do not turn the unlocking cam (the arrow or mark on the unlocking cam head) past the position marked FREE. If it is turned too far, there is a danger of damaging the unlocking cam.
- For safety reasons, the unlocking cam is constructed so that it cannot be fixed in the unlocked condition.



[Principle]

If the unlocking cam is turned clockwise with an adjustable angle wrench or socket wrench, etc., the release piston is pushed back and the lock is released. Since the lever will return to its original position and become locked again when it is released, it should be held in this position for as long as unlocking is required.





Be sure to read this before handling the products.

Refer to page 9 for safety instructions and pages 10 to 19 for actuator and auto switch precautions.

### Maintenance

# **⚠** Caution

# 1. Lock units for the CNS series are replaceable.

To order replacement lock units for the CNS series, use the order numbers given in the table below.

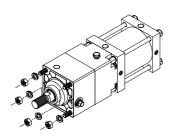
Bore size (mm)	Lock unit part no.
125	CNS125D-UA
140	CNS140D-UA
160	CNS160D-UA

### 2. How to replace lock unit

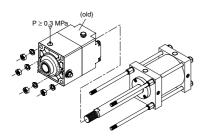
Loosen the tie-rod nuts (4 pcs.) in the cylinder rod side by using a socket wrench.

For the applicable socket, refer to the table below.

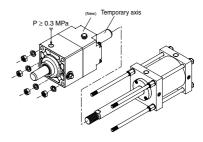
Bore size (mm)	Nut	Width across flats	Socket
125, 140	JIS B 1181 Class 2 M14 x 1.5	22	JIS B 4636 socket 22
160	JIS B 1181 Class 2 M16 x 1.5	24	JIS B 4636 socket 24



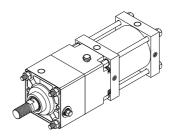
2) Apply compressed air of 0.3 MPa or more to the unlocking port, and remove the lock unit.



 Similarly, apply 0.3 MPa or more of compressed air to the unlocking port of the new lock unit, and replace the new lock unit's temporary axis with the previous piston rod assembly.



 Tighten the tie-rod nuts (4 pcs.) on the rod side of the cylinder using a socket wrench.



# **△**Warning

# Never disassemble a lock unit of CNS series.

- 1. Since a heavy duty spring is contained in the unit, there is a serious hazard, such as the possibility of parts being ejected, if disassembly is performed incorrectly. Therefore, do not loosen or remove the hexagon socket head cap screws which secure cover A and cover B.
- 2. Be sure to contact SMC regarding disassembly or repair, etc.

